

- natural numbers are represented in unary

e.g.

n	$\bar{n}$
0	1
1	11
2	111
$\vdots$	$\vdots$

- consecutive numbers on the input are separated by a \$
- the TM starts its computation with the head placed on a \$ preceding the first number

↑ q_0

e.g. if $f(2, 0, 3) = 4$

	1	1	1	1	1			
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1) there is a single final state q_f
2) the only f

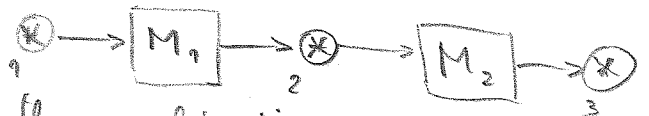
2) the only transition from q_0 is

3) there are no trans if $\sigma(q_0, \phi) = (q_i, \psi, R_i)$

4) The computation loops whenever $f(n) \uparrow$, i.e. $f(n)$ is undefined

This allows us to sequentially compose TMs:

represented by the diagram



1... initial state of M_1 end of the combination

3... final

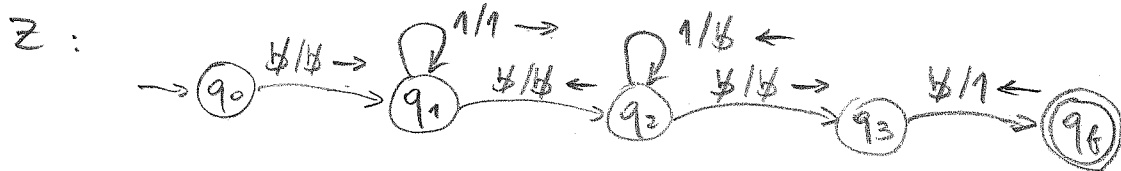
2. ... final state of M_1 is also the initial state of M_2

1) Construct a TM computing the successor function

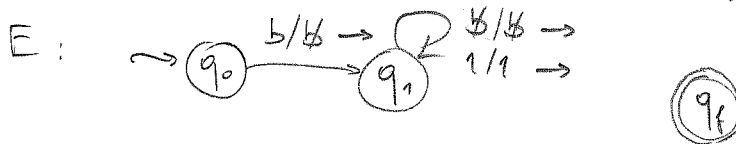
$$O(n) = n + 1$$



2) Construct a TM computing the zero function $z(n) = 0$



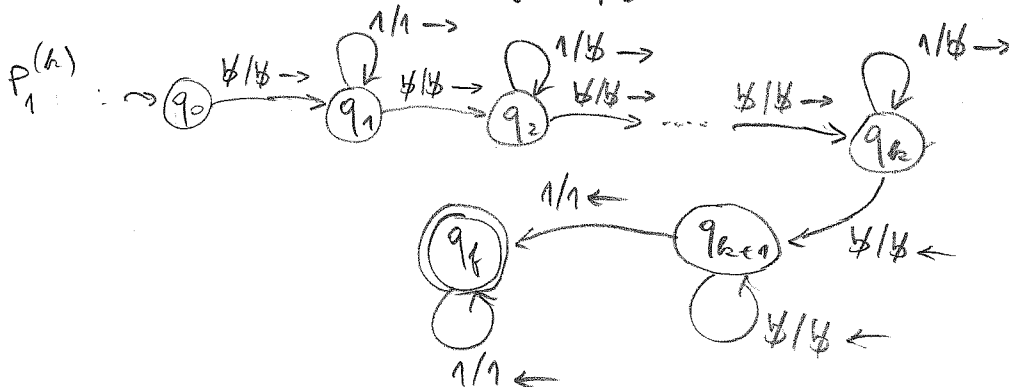
3) Construct a TM computing the empty function $e(n) \uparrow$
i.e., the function that is undefined for every $n \in \mathbb{N}$



The k -variable projection function $\pi_i^{(k)}$ is defined as

$$\pi_i^{(k)}(n_1, \dots, n_k) = n_i \quad (\text{for } 1 \leq i \leq k)$$

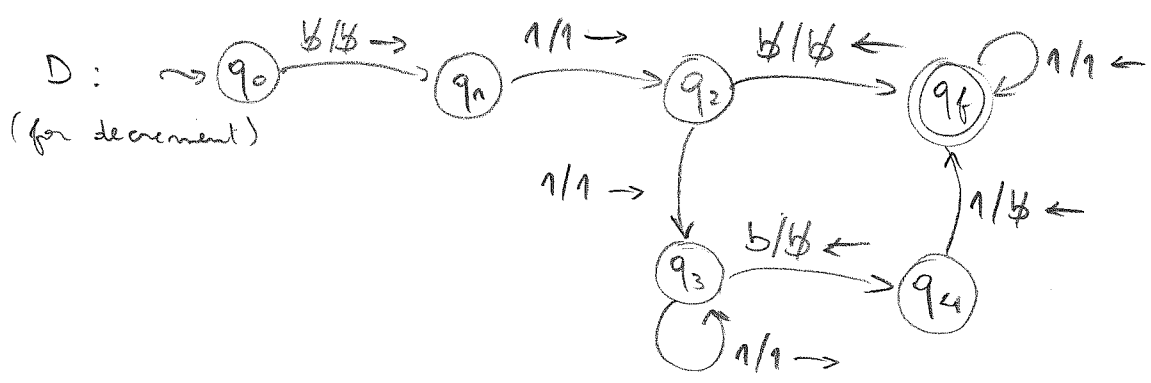
4) Construct a TM computing $\pi_1^{(k)}$



Note $\pi_1^{(1)}$ is also called the identity function $id(n) = n$

5) Construct a TM computing the predecessor function

$$\text{pred}(n) = \begin{cases} 0 & \text{if } n=0 \\ n-1 & \text{if } n>0 \end{cases}$$

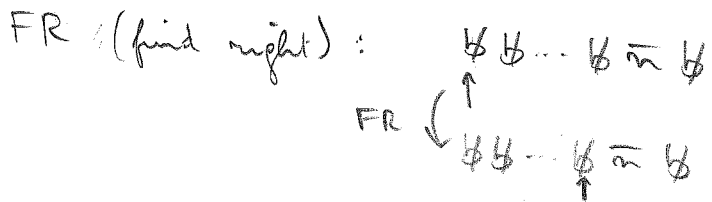
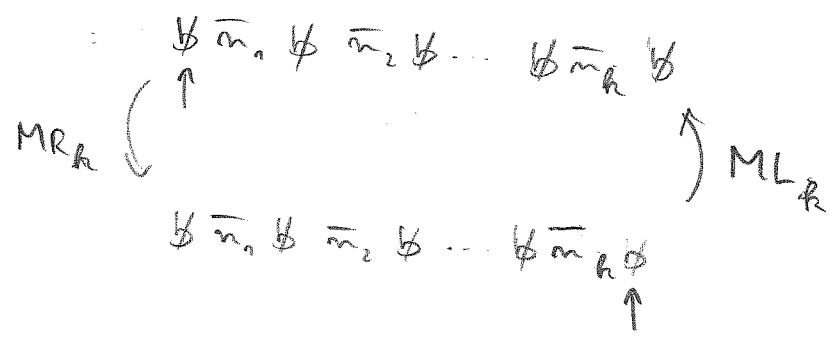
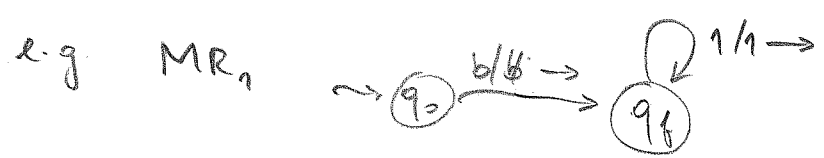


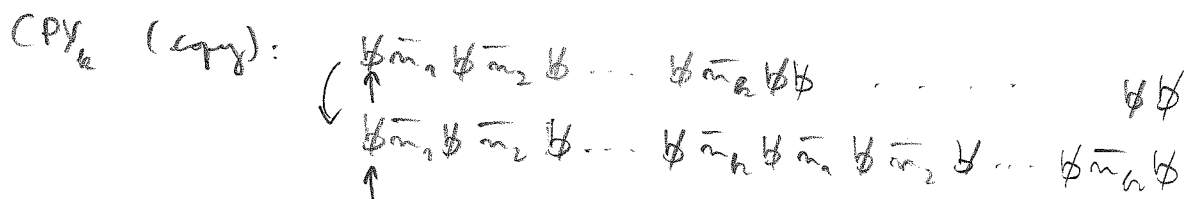
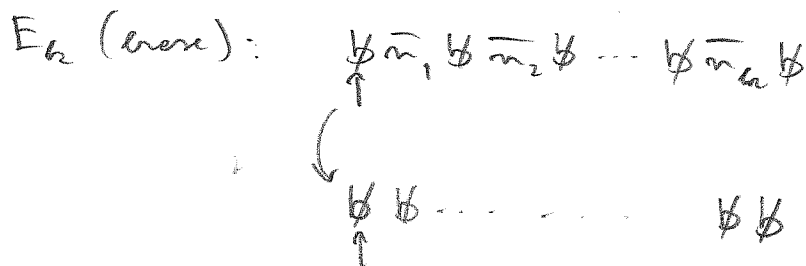
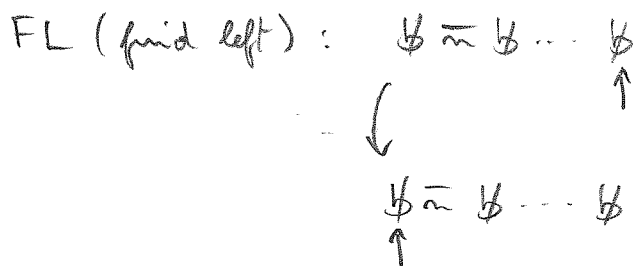
6) Using sequential composition, construct a TM computing the constant function $c(n) = 1$



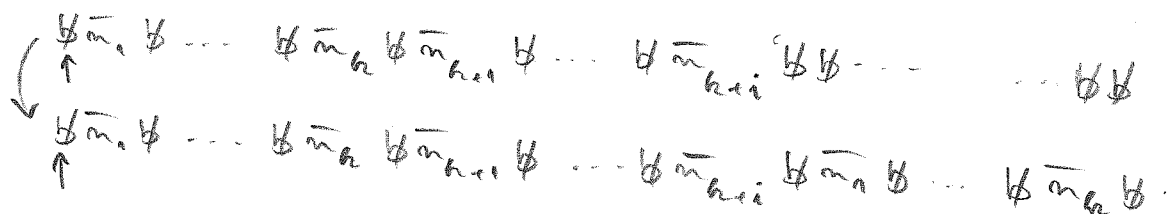
We now define some TMs that can be used as macros:

MR_k : move the tape head to the right through k consecutive natural numbers



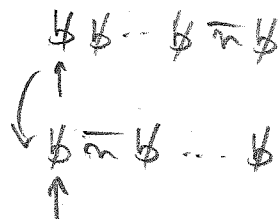


$CPY_{k,i}$ (copy through i numbers)

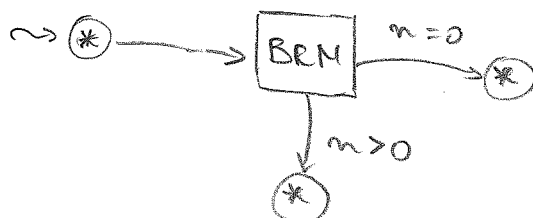


for CPY_k and $CPY_{k,i}$ the blank portion following $\bar{m}_1 \$ \dots \$ \bar{m}_n$ is assumed to be long enough to contain the copy.

T (translate)



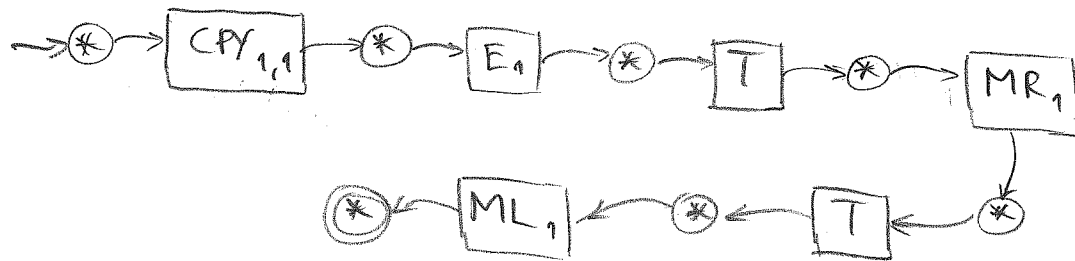
BRN (branch on zero)



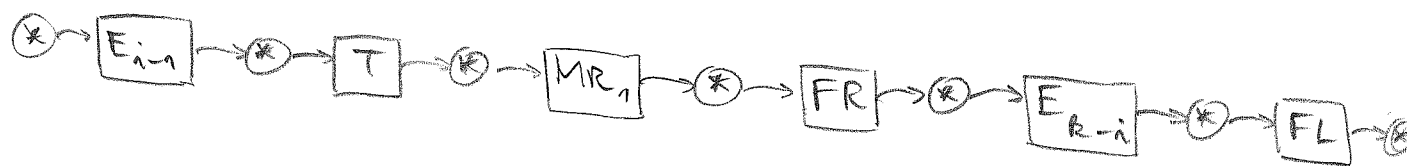
it does not alter the tape or change the head position

7) Using composition and the defined macros, construct

a TM INT (interchange): $\$ \bar{n} \$ \bar{m} \$ \bar{n}^{n+1} \$$
 $\uparrow$
 $\$ \bar{m} \$ \bar{n} \$ \bar{n}^{n+1} \$$



8) Using composition and the defined macros, construct a TM for $P_i^{(k)}$



Function composition:

E5.6

$$\text{Set } g_i : \mathbb{N}^k \rightarrow \mathbb{N} \text{ for } 1 \leq i \leq n$$

$$h : \mathbb{N}^n \rightarrow \mathbb{N}$$

The composition of h with $g_1, \dots, g_n$, written

$$f = h \circ (g_1, \dots, g_n)$$

is the function $f : \mathbb{N}^k \rightarrow \mathbb{N}$ defined by

$$f(x_1, \dots, x_k) = h(g_1(x_1, \dots, x_k), \dots, g_n(x_1, \dots, x_k))$$

The function $f(x_1, \dots, x_k)$ is undefined if either

1) $g_i(x_1, \dots, x_k) \uparrow$ for some $i \in \{1, \dots, n\}$

2) $g_i(x_1, \dots, x_k) = y_i$ for $i \in \{1, \dots, n\}$ and $h(y_1, \dots, y_n) \uparrow$

We show that the composition of Turing-computable functions is also Turing-computable.

Exercise: given $g_1 : \mathbb{N}^3 \rightarrow \mathbb{N}$, $g_2 : \mathbb{N}^3 \rightarrow \mathbb{N}$, $h : \mathbb{N}^2 \rightarrow \mathbb{N}$

and TMs G_1, G_2, H computing respectively g_1, g_2, h ,

construct a TM computing $h \circ (g_1, g_2)$.

Use macros and TM composition, and construct the configurations obtained after every macro application.

macro configuration

$$\underline{\phi} \bar{m}_1 \phi \bar{m}_2 \phi \bar{m}_3 \phi$$

$$CPY_3 \quad \underline{\phi} \bar{m}_1 \phi \bar{m}_2 \phi \bar{m}_3 \phi \bar{m}_1 \phi \bar{m}_2 \phi \bar{m}_3 \phi$$

$$MR_3 \quad \phi \quad - \quad \phi \quad - \quad \phi$$

$$G_1 \quad \phi \quad - \quad \underline{\phi} \bar{y}_1 \phi$$

(where $y_1 = g_1(m_1, m_2, m_3)$)

$$ML_3 \quad \underline{\phi} \bar{m}_1 \phi \bar{m}_2 \phi \bar{m}_3 \phi \bar{y}_1 \phi$$

$$CPY_{3,1} \quad \underline{\phi} \quad - \quad \phi \bar{m}_1 \phi \bar{m}_2 \phi \bar{m}_3 \phi$$

$$MR_4 \quad \phi \quad - \quad \underline{\phi} \quad - \quad \phi$$

$$G_2 \quad \phi \quad - \quad \underline{\phi} \bar{y}_1 \underline{\phi} \bar{y}_2 \phi$$

(where $y_2 = g_2(m_1, m_2, m_3)$)

$$ML_1 \quad \phi \quad - \quad \underline{\phi} \bar{y}_1 \phi \bar{y}_2 \phi$$

$$H \quad \phi \quad - \quad \underline{\phi} \bar{z} \phi$$

(where $z = h(y_1, y_2)$)

$$ML_3 \quad \underline{\phi} \quad - \quad \phi \bar{z} \phi$$

$$E_3 \quad \underline{\phi} \phi \quad - \quad \phi \bar{z} \phi$$

$$T \quad \phi \bar{z} \phi$$