Ontology and Database Systems: Knowledge Representation and Ontologies Part 2: Description Logics

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A.Y. 2016/2017



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Part 2

Description Logics

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- Basic definitions
- Hardness and completeness
- Most important complexity classes

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 Basic definitions
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[J.E. Hopcroft 2007; Papadimitriou 1994]

Computational complexity theory aims at understanding how difficult it is to solve specific problems.

- A **problem** is considered as an (in general infinite) set of instances of the problem, each encoded in some meaningful (i.e., compact) way.
- Standard complexity theory deals with **decision problems**: i.e., problems that admit a yes/no answer.
- Algorithm that solves a decision problem:
 - input: an instance of the problem
 - output: yes or no
- The difficulty (complexity) is measured in terms of the amount of resources (time, space) that the algorithm needs to solve the problem.
 → complexity of the algorithm, or upper bound
- To measure the complexity of the problem, we consider the best possible algorithm that solves it.
 - \rightsquigarrow lower bound

- Worst-case complexity analysis: the complexity is measured in terms of a (complexity) function *f*:
 - argument: the size n of an instance of the problem (i.e., the length of its encoding)
 - $\bullet\,$ result: the amount f(n) of time/space needed in the worst-case to solve an instance of size n
- The **asymptotic behaviour** of the complexity function when *n* grows is considered.
- To abstract away from contingent issues (e.g., programming language, processor speed, etc.), we refer to an abstract computing model: **Turing Machines** (TMs).

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Complexity of	classes				

To achieve robustness wrt encoding issues, usually one does not consider specific complexity functions f, but rather families C of complexity functions, giving rise to complexity classes.

Def.: A time/space complexity class C

... is the set of all problems P such that an instance of P of size n can be solved in time/space at most C(n).

Note: Consider a (decision) problem P, and an encoding of the instances of P into strings over some alphabet Σ .

Once we fix such an encoding, the problem actually corresponds to a language L_P , namely the set of strings encoding those instances of the problem for which the answer is yes.

Hence, in the technical sense, a complexity class is actually a set of languages.

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Reductions				

To establish lower bounds on the complexity of problems, we make use of the notion of reduction:

Def.: A reduction from a problem P_1 to a problem P_2

... is a function R (the reduction) from instance of P_1 to instances of P_2 such that:

- \bigcirc R is efficiently computable (i.e., in logarithmic space), and
- 2 An instance I of P_1 has answer yes iff R(I) has answer yes.

 P_1 reduces to P_2 if there is a reduction R from P_1 to P_2 .

Intuition: If P_1 reduces to P_2 , then P_2 is at least as difficult as P_1 , since we can solve an instance I of P_1 by reducing it to the instance R(I) of P_2 and then solve R(I).

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Def.: A problem P is **hard** for a complexity class $\ensuremath{\mathcal{C}}$

 \ldots if every problem in C can be reduced to P.

Def.: A problem P is **complete** for a complexity class \mathcal{C} if

- \bigcirc it is hard for \mathcal{C} , and
- $\textcircled{0} \quad \text{it belongs to } \mathcal{C}$

Intuitively, a problem that is complete for C is among the hardest problems in C.

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 Tractability and intractability:
 PTIME and NP

Def.: PTIME

Set of problems solvable in polynomial time by a deterministic TM.

- These problems are considered tractable, i.e., solvable for large inputs.
- Is a robust class (PTIME computations compose).

Def.: NP

Set of problems solvable in polynomial time by a non-deterministic TM.

- These problems are believed intractable, i.e., unsolvable for large inputs.
- The best known algorithms actually require exponential time.
- Corresponds to a large class of practical problems, for which the following type of algorithm can be used:
 - **1** Non-deterministically guess a possible solution of polynomial size.
 - One of the second se

Complement of problems in $\operatorname{NP}\colon\operatorname{CONP}$

Def.: CONP

Set of problems whose complement is in $\rm NP$, i.e., problems for which determining whether an instance admits a no answer is in $\rm NP.$

- For problems whose complexity is characterized in terms of a non-deterministic TM, solving the problem and solving its complement might be different.
- The reason for this is that a yes answer is returned if there **exists** a non-deterministic computation-path of the TM that leads to acceptance.
- Instead, a no answer requires that all non-deterministic computation-paths of the TM lead to rejection.
- \bullet Specifically, ${\rm CONP}$ is believed to be different from both ${\rm NP}$ and ${\rm PTIME}.$

Computational complexity Most important complexity classes Part 2: Description Logics Complexity classes above NP

Def.: PSPACE

Set of problems solvable in polynomial space by a deterministic TM.

- Polynomial space is "not really good", since these problems may require exponential time.
- These problems are considered to be more difficult than NP problems.
- Practical algorithms and heuristics work less well than for NP problems.

Def: EXPTIME

Set of problems solvable in exponential time by a deterministic TM.

- This is the first provably intractable complexity class.
- These problems are considered to be very difficult. ۲

Def.: NEXPTIME

Set of problems solvable in exponential time by a non-deterministic TM.

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Complexity	classes below	v PT	IME		

Def.: LOGSPACE and NLOGSPACE

Set of problems solvable in logarithmic space by a (non-)deterministic TM.

- Note: when measuring the space complexity, the size of the input does not count, and only the working memory (TM tape) is considered.
- Note 2: logarithmic space computations compose (this is not trivial).
- Correspond to reachability in undirected and directed graphs, respectively.

Def.: AC^0

Set of problems solvable in constant time using a polynomial number of processors.

- These problems are solvable efficiently even for very large inputs.
- Corresponds to the complexity of model checking a fixed FO formula when the input is the model only.

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Relationship between the complexity classes

The following relationships are known:

```
\begin{array}{rcl} AC^{0} \ \subsetneq \ LogSpace \ \subseteq \ NLogSpace \ \subseteq \ PTime \ \subseteq \\ & \ \subseteq \ NP \ \subseteq \ PSpace \ \subseteq \\ & \ \subseteq \ ExpTime \ \subseteq \ NExpTime \end{array}
```

Moreover, we know that $\mathrm{PTIME}\ \subsetneq\ \mathbf{ExpTIME}.$

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Description Logics (DLs) [Baader et al. 2003] are **logics** specifically designed to represent and reason on structured knowledge.

The domain of interest is composed of objects and is structured into:

- concepts, which correspond to classes, and denote sets of objects
- roles, which correspond to (binary) relationships, and denote binary relations on objects

The knowledge is asserted through so-called assertions, i.e., logical axioms.

Description Logics stem from early days knowledge representation formalisms (late '70s, early '80s):

- Semantic Networks: graph-based formalism, used to represent the meaning of sentences.
- Frame Systems: frames used to represent prototypical situations, antecedents of object-oriented formalisms.

Problems: no clear semantics, reasoning not well understood.

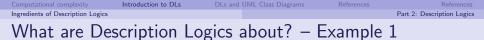
Description Logics (a.k.a. Concept Languages, Terminological Languages) developed starting in the mid '80s, with the aim of providing semantics and inference techniques to knowledge representation systems.

What are Description Logics about?

Abstractly, DLs allow one to predicate about labeled directed graphs:

- Nodes represent real world objects.
- Node labels represent types/categories of objects.
- Edges represent relations between (pairs of) objects, or between objects and values
- Edge labels represent the types of relations between objects, or between objects and values.

Every fragment of the world that can be abstractly represented in terms of a labeled directed graph is a good candidate for being represented by DLs.





Exercise

Represent Metro lines in Milan in a labelled directed graph.

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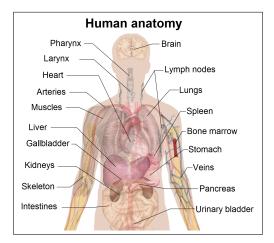
Exercise

Represent some aspects of Facebook as a labelled directed graph.

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What are Description Logics about? – Example 3



Exercise

Represent some aspects of human anatomy as a labelled directed graph.

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What are Description Logics about? - Example 4



Exercise

Represent some aspects of document classification as a labelled directed graph.

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A **DL** is characterized by:

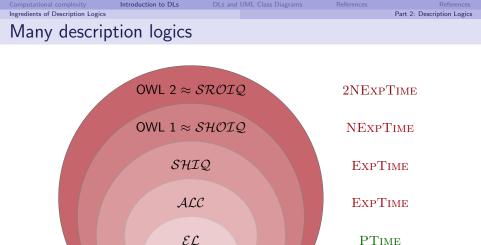
A description language: how to form concepts and roles Human □ Male □ ∃hasChild □ ∀hasChild.(Doctor ⊔ Lawyer)

 A mechanism to specify knowledge about concepts and roles (i.e., a TBox)

 T = { Father ≡ Human □ Male □ ∃hasChild, HappyFather □ Father □ ∀hasChild.(Doctor ⊔ Lawyer) }

A mechanism to specify properties of objects (i.e., an ABox)
A = { HappyFather(john), hasChild(john,mary) }

A set of inference services: how to reason on a given KB
 T ⊨ HappyFather ⊑ ∃hasChild.(Doctor ⊔ Lawyer)
 T ∪ *A* ⊨ (Doctor ⊔ Lawyer)(mary)



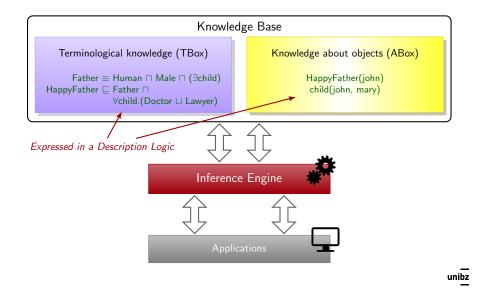
DL-Lite

PTIME

NLOGSPACE



Architecture of a Description Logic system



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Description I	anguage			

A description language provides the means for defining:

- concepts, corresponding to classes: interpreted as sets of objects;
- roles, corresponding to relationships: interpreted as binary relations on objects.

To define concepts and roles:

- We start from a (countably infinite) alphabet of concept names and role names, forming so called **atomic concepts and roles**.
- Then, by applying specific **constructors**, we can build **complex concepts** and **roles**, starting from the atomic ones.

A **description language** is characterized by the set of constructs that are available for that.

Formal semantics of a description language

The formal semantics of DLs is given in terms of interpretations.

Def.: An interpretation $\mathcal{I} = (\Delta^{\mathcal{I}}, \cdot^{\mathcal{I}})$ consists of:

- a nonempty set $\Delta^{\mathcal{I}}$, called the interpretation domain (of \mathcal{I})
- an interpretation function $\cdot^{\mathcal{I}}$, which maps
 - each atomic concept A to a subset $A^{\mathcal{I}}$ of $\Delta^{\mathcal{I}}$
 - each atomic role P to a subset $P^{\mathcal{I}}$ of $\Delta^{\mathcal{I}} \times \Delta^{\mathcal{I}}$

The interpretation function is extended to complex concepts and roles according to their syntactic structure.

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Concept con	structors			

Construct	struct Syntax Example		Semantics	
atomic concept	A	Doctor	$A^{\mathcal{I}} \subseteq \Delta^{\mathcal{I}}$	
atomic role	Р	hasChild	$P^{\mathcal{I}} \subseteq \Delta^{\mathcal{I}} \times \Delta^{\mathcal{I}}$	
atomic negation	$\neg A$	¬Doctor	$\Delta^{\mathcal{I}} \setminus A^{\mathcal{I}}$	
conjunction	$C \sqcap D$	$Hum \sqcap Male$	$C^{\mathcal{I}} \cap D^{\mathcal{I}}$	
(unqual.) exist. res.	$\exists R$	∃hasChild	$\{ o \mid \exists o'. (o, o') \in R^{\mathcal{I}} \}$	
value restriction	$\forall R.C$	∀hasChild.Male	$\{o \mid \forall o'. (o, o') \in R^{\mathcal{I}} \to o' \in C^{\mathcal{I}}\}$	
bottom			Ø	

(C, D denote arbitrary concepts and R an arbitrary role)

The above constructs form the basic language \mathcal{AL} of the family of \mathcal{AL} languages.

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Additional concept and role constructors

Construct	\mathcal{AL}	Syntax	Semantics
disjunction	U	$C \sqcup D$	$C^{\mathcal{I}} \cup D^{\mathcal{I}}$
top		Т	$\Delta^{\mathcal{I}}$
qual. exist. res.	E	$\exists R.C$	$\{ o \mid \exists o'. (o, o') \in R^{\mathcal{I}} \land o' \in C^{\mathcal{I}} \}$
(full) negation	C	$\neg C$	$\Delta^{\mathcal{I}} \setminus C^{\mathcal{I}}$
number	\mathcal{N}	$(\geq k R)$	$\{ o \mid \#\{o' \mid (o, o') \in R^{\mathcal{I}}\} \ge k \}$
restrictions		$(\leq k R)$	$\{ o \mid \#\{o' \mid (o, o') \in R^{\mathcal{I}}\} \le k \}$
qual. number	Q	$(\geq k R.C)$	$\{ o \mid \#\{o' \mid (o, o') \in R^{\mathcal{I}} \land o' \in C^{\mathcal{I}} \} \ge k \}$
restrictions		$(\leq k R.C)$	$\{ o \mid \#\{o' \mid (o, o') \in R^{\mathcal{I}} \land o' \in C^{\mathcal{I}} \} \le k \}$
inverse role	\mathcal{I}	R^{-}	$\{ (o, o') \mid (o', o) \in R^{\mathcal{I}} \}$
role closure	reg	R^*	$(R^{\mathcal{I}})^*$

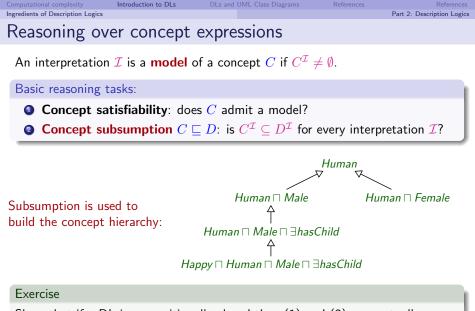
Many different DL constructs and their combinations have been investigated.

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Further exan	nples of DL	constructs		

- Disjunction: $\forall hasChild.(Doctor \sqcup Lawyer)$
- Qualified existential restriction: $\exists hasChild.Doctor$
- Full negation: \neg (*Doctor* \sqcup *Lawyer*)
- Number restrictions: $(\geq 2 \text{ hasChild}) \sqcap (\leq 1 \text{ sibling})$
- Qualified number restrictions: $(\geq 2 hasChild. Doctor)$
- Inverse role: ∀hasChild⁻.Doctor
- Reflexive-transitive role closure: $\exists hasChild^*.Doctor$



Show that if a DL is propositionally closed then (1) and (2) are mutually reducible.

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Complexity of reasoning over concept expressions

Complexity of concept satisfiability: [I	Donini et al. 1997]	
$\mathcal{AL}, \mathcal{ALN}$	PTIME	
ALU, ALUN	NP-complete	
ALE	coNP-complete	
ALC, ALCN, ALCI, ALCQI	PSPACE-complete	

Observations:

- Two sources of complexity:
 - union (\mathcal{U}) of type NP,
 - qualified existential quantification (\mathcal{E}) of type coNP.

When they are combined, the complexity jumps to $\ensuremath{\operatorname{PSPACE}}$.

• Number restrictions (\mathcal{N}) do not add to the complexity.

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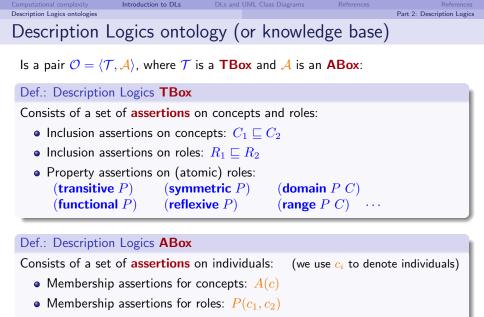
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We have seen how to build complex **concept and roles expressions**, which allow one to denote classes with a complex structure.

However, in order to represent real world domains, one needs the ability to **assert properties** of classes and relationships between them (e.g., as done in UML class diagrams).

The assertion of properties is done in DLs by means of an **ontology** (or knowledge base).



• Equality and distinctness assertions: $c_1 \approx c_2$, $c_1 \not\approx c_2$

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Note: We use $C_1 \equiv C_2$ as an abbreviation for $C_1 \sqsubset C_2$, $C_2 \sqsubset C_1$.

TBox assertions:

- Inclusion assertions on concepts:
 - Father
 ≡
 Human ⊓ Male ⊓ ∃hasChild

 HappyFather
 ⊑
 Father ⊓ ∀hasChild.(Doctor ⊔ Lawyer ⊔ HappyPerson)

 HappyAnc
 ⊑
 ∀descendant.HappyFather

 Teacher
 ⊑
 ¬Doctor ⊓ ¬Lawyer

 $hasFather \sqsubseteq hasChild^-$

• Property assertions on roles: (transitive descendant), (reflexive descendant), (functional hasFather)

ABox membership assertions:

• Teacher(mary), hasFather(mary, john), HappyAnc(john)

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Semantics of a Description Logics ontology

The semantics is given by specifying when an interpretation \mathcal{I} satisfies an assertion α , denoted $\mathcal{I} \models \alpha$.

TBox Assertions:

- $\mathcal{I} \models C_1 \sqsubseteq C_2$ if $C_1^{\mathcal{I}} \subseteq C_2^{\mathcal{I}}$.
- $\mathcal{I} \models R_1 \sqsubset R_2$ if $R_1^{\mathcal{I}} \subseteq R_2^{\mathcal{I}}$.
- $\mathcal{I} \models (\text{prop } P)$ if $P^{\mathcal{I}}$ is a relation that has the property prop. (Note: domain and range assertions can be expressed by means of concept inclusion assertions.)

ABox Assertions

We need first to extend the interpretation function \mathcal{I} , so that it maps each individual c to an element $c^{\mathcal{I}}$ of $\Delta^{\mathcal{I}}$.

- $\mathcal{I} \models A(c)$ if $c^{\mathcal{I}} \in A^{\mathcal{I}}$. • $\mathcal{I} \models c_1 \approx c_2$ if $c_1^{\mathcal{I}} = c_2^{\mathcal{I}}$.
- $\mathcal{I} \models P(c_1, c_2)$ if $(c_1^{\mathcal{I}}, c_2^{\mathcal{I}}) \in P^{\mathcal{I}}$.

• $\mathcal{I} \models c_1 \not\approx c_2$ if $c_1^{\mathcal{I}} \neq c_2^{\mathcal{I}}$.

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Model of a Description Logics ontology

Def.: Model

An interpretation \mathcal{I} is a **model** of:

- an assertion α , if it satisfies α .
- a TBox \mathcal{T} , if it satisfies all assertions in \mathcal{T} .
- an ABox \mathcal{A} , if it satisfies all assertions in \mathcal{A} .
- an ontology $\mathcal{O} = \langle \mathcal{T}, \mathcal{A} \rangle$, if it is a model of both \mathcal{T} and \mathcal{A} .

Note: We use $\mathcal{I} \models \beta$ to denote that interpretation \mathcal{I} is a **model** of β (where β stands for an assertion, TBox, ABox, or ontology).

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Interpretation	n of individu	uals		

We may make some assumptions on how individuals are interpreted.

Unique name assumption (UNA)

When c_1 and c_2 are two individuals such that $c_1 \neq c_2$, then $c_1^{\mathcal{I}} \neq c_2^{\mathcal{I}}$.

Note: When the UNA holds, equality and distinctness assertions are meaningless.

Standard name assumption (SNA)

The UNA holds, and moreover individuals are interpreted in the same way in all interpretations.

Hence, we may assume that $\Delta^{\mathcal{I}}$ contains the set of individuals, and that for each interpretation \mathcal{I} , we have that $c^{\mathcal{I}} = c$ (then, c is called a standard name).

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Logical impli	cation			

The fundamental reasoning service from which all other ones can be easily derived is \ldots

Def.: Logical implication An ontology \mathcal{O} logically implies an assertion α , written $\mathcal{O} \models \alpha$, if α is satisfied by all models of \mathcal{O} .

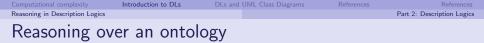
We can provide an analogous definition for a TBox \mathcal{T} instead of an ontology \mathcal{O} .

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TBox reason	ing			

- **TBox Satisfiability:** \mathcal{T} is satisfiable, if it admits at least one model.
- Concept Satisfiability: C is satisfiable wrt T, if there is a model I of T such that C^I is not empty, i.e., T ⊭ C ≡ ⊥.
- Subsumption: C_1 is subsumed by C_2 wrt \mathcal{T} , if for every model \mathcal{I} of \mathcal{T} we have $C_1^{\mathcal{I}} \subseteq C_2^{\mathcal{I}}$, i.e., $\mathcal{T} \models C_1 \sqsubseteq C_2$.
- Equivalence: C_1 and C_2 are equivalent wrt \mathcal{T} if for every model \mathcal{I} of \mathcal{T} we have $C_1^{\mathcal{I}} = C_2^{\mathcal{I}}$, i.e., $\mathcal{T} \models C_1 \equiv C_2$.
- **Disjointness:** C_1 and C_2 are disjoint wrt \mathcal{T} if for every model \mathcal{I} of \mathcal{T} we have $C_1^{\mathcal{I}} \cap C_2^{\mathcal{I}} = \emptyset$, i.e., $\mathcal{T} \models C_1 \sqcap C_2 \equiv \bot$.
- Functionality implication: A functionality assertion (funct R) is logically implied by \mathcal{T} if for every model \mathcal{I} of \mathcal{T} , we have that $(o, o_1) \in R^{\mathcal{I}}$ and $(o, o_2) \in R^{\mathcal{I}}$ implies $o_1 = o_2$, i.e., $\mathcal{T} \models (\text{funct } R)$.

Analogous definitions hold for role satisfiability, subsumption, equivalence, and disjointness.

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- **Ontology Satisfiability:** Verify whether an ontology \mathcal{O} is satisfiable, i.e., whether \mathcal{O} admits at least one model.
- Concept Instance Checking: Verify whether an individual c is an instance of a concept C in every model of \mathcal{O} , i.e., whether $\mathcal{O} \models C(c)$.
- Role Instance Checking: Verify whether a pair (c_1, c_2) of individuals is an instance of a role R in every model of \mathcal{O} , i.e., whether $\mathcal{O} \models R(c_1, c_2)$.
- Query Answering: see later ...

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Reasoning in Description Logics – Example

TBox:

- Inclusion assertions on concepts:
 - Father \equiv Human \sqcap Male \sqcap \exists hasChildHappyFather \sqsubseteq Father \sqcap \forall hasChild.(Doctor \sqcup Lawyer \sqcup HappyPerson)HappyAnc \sqsubseteq \forall descendant.HappyFatherTeacher \sqsubseteq \neg Doctor \sqcap \neg Lawyer

```
hasFather \sqsubseteq hasChild^-
```

 Property assertions on roles: (transitive descendant), (reflexive descendant), (functional hasFather)

The above TBox logically implies: $HappyAncestor \sqsubseteq Father$.

• Membership assertions:

Teacher(mary), hasFather(mary, john), HappyAnc(john)

The above TBox and ABox logically imply: *HappyPerson*(mary)

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Relationship among TBox reasoning tasks

The TBox reasoning tasks are mutually **reducible** to each other, provided the description language is propositionally closed:

TBox satisfiability to concept satisfiability to concept non-subsumption

 $\begin{array}{lll} \mathcal{T} \text{ satisfiable} & \text{iff} & \mathcal{T} \not\models \top \equiv \bot & \text{iff} & \text{not} \ \mathcal{T} \models \top \sqsubseteq \bot \\ & (\text{i.e., } \top \text{ satisfiable w.r.t. } \mathcal{T}) \end{array}$

Concept subsumption to concept unsatisfiability

$$\mathcal{T} \models C_1 \sqsubseteq C_2 \quad \text{iff} \quad \mathcal{T} \models C_1 \sqcap \neg C_2 \equiv \bot \\ (\text{i.e., } C_1 \sqcap \neg C_2 \text{ unsatisfiable w.r.t. } \mathcal{T})$$

Concept satisfiability to TBox satisfiability

$$\mathcal{T} \not\models C \equiv \bot \quad \text{iff} \quad \mathcal{T} \cup \{ \top \sqsubseteq \exists P_{new} \sqcap \forall P_{new}.C \} \text{ satisfiable} \\ (\text{where } P_{new} \text{ is a new atomic role})$$

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 Relationship
 among reasoning tasks
 TBox reasoning can be reduced to reasoning over an ontology:
 TBox
 TBox</

Concept satisfiability to ontology satisfiability

 $\begin{array}{ll} C \text{ satisfiable wrt } \mathcal{T} & \text{iff} & \langle \mathcal{T} \cup \{A_{new} \sqsubseteq C\}, \ \{A_{new}(c_{new})\} \rangle \text{ is satisfiable} \\ & (\text{where } A_{new} \text{ is a new atomic concept and } c_{new} \text{ is a new individual}) \end{array}$

Exercise

Show mutual reductions between the remaining (TBox and ontology) reasoning tasks.

Internalization of the TBox:

- In some (very expressive) DLs, it is possible to reduce reasoning wrt a TBox to reasoning over concept expressions only, i.e., the whole TBox can be internalized into a single concept.
- Whether this is possible depends on the available role and concept constructors, and the details differ for each DL.

Complexity of reasoning over DL ontologies

We will see later that reasoning over DL ontologies is much more complex than reasoning over concept expressions:

Bad news:

• without restrictions on the form of TBox assertions, reasoning over DL ontologies is already ExpTIME-hard, even for very simple DLs (see, e.g., [Donini 2003]).

Good news:

- We can add a lot of expressivity (i.e., essentially all DL constructs seen so far), while still staying within the EXPTIME upper bound.
- There are DL reasoners that perform reasonably well in practice for such DLs (e.g, Racer, Pellet, Fact++, ...) [Möller and Haarslev 2003].

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Relationship with First Order Logic

Most DLs are well-behaved fragments of First Order Logic.

To translate an ALC ontology to FOL:

- Introduce: a unary predicate A(x) for each atomic concept A a binary predicate P(x, y) for each atomic role P
- 2 Translate complex concepts as follows, using translation functions t_x , one for each variable x:
 - $t_r(\mathbf{A}) = A(x)$ $t_r(C \sqcap D) = t_r(C) \land t_r(D)$ $t_r(\neg C) = \neg t_r(C)$ $t_r(C \sqcup D) = t_r(C) \lor t_r(D)$ $t_r(\exists P.C) = \exists y. P(x, y) \land t_u(C)$ $t_x(\forall P, C) = \forall u, P(x, u) \rightarrow t_u(C)$ (with y a new variable)
- Translate a TBox $\mathcal{T} = \bigcup_i \{ C_i \subseteq D_i \}$ as the FOL theory:

 $\Gamma_{\mathcal{T}} = \bigcup_{i} \{ \forall x. t_x(C_i) \to t_x(D_i) \}$

• Translate an ABox $\mathcal{A} = \bigcup_i \{ A_i(c_i) \} \cup \bigcup_i \{ P_j(c'_i, c''_i) \}$ as the FOL th.: $\Gamma_{\mathcal{A}} = \bigcup_{i} \{ A_i(c_i) \} \cup \bigcup_{i} \{ P_i(c'_i, c''_i) \}$

Relationship with First Order Logic – Exercise

Translate the following \mathcal{ALC} concepts and assertions into FOL formulas:

- Father \cap \delta child.(Doctor \cap Manager)
- ∃manages.(Company □ ∃employs.Doctor)
- Father □ ∀child.(Doctor ⊔ ∃manages.(Company □ ∃employs.Doctor))
- Person $\sqcap \forall$ child. Happy $\sqsubseteq \exists$ child. \forall child. Happy

Solution:

- $\textbf{Stather}(x) \land \forall y. (\textit{child}(x, y) \rightarrow (\textit{Doctor}(y) \lor \textit{Manager}(y)))$
- Father(x) $\land \forall y. (child(x, y) \rightarrow (Doctor(y) \lor \exists w. (manages(y, w) \land (Company(w) \land \exists z. (employs(w, z) \land Doctor(z))))))$
- $\forall x. (Person(x) \land \forall y. child(x, y) \rightarrow Happy(y)) \rightarrow (\exists y. child(x, y) \land \forall z. child(y, z) \rightarrow Happy(z))$

There is a direct correspondence between DL reasoning services and FOL reasoning services:

 $\begin{array}{lll} C \text{ is satisfiable} & \text{iff} & \text{its translation } t_x(C) \text{ is satisfiable} \\ & C \sqsubseteq D & \text{iff} & t_x(C) \to t_x(D) \text{ is valid} \\ \\ C \text{ is satisfiable w.r.t. } \mathcal{T} & \text{iff} & \Gamma_{\mathcal{T}} \cup \{ \exists x. t_x(C) \} \text{ is satisfiable} \\ & \mathcal{T} \models C \sqsubseteq D & \text{iff} & \Gamma_{\mathcal{T}} \models \forall x. (t_x(C) \to t_x(D)) \end{array}$

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DLs as fragments of First Order Logic

The previous translation shows us that DLs are a fragment of First Order Logic.

In particular, we can translate complex concepts using just two translation functions t_x and t_y (thus reusing the same variables):

$t_x(A) = A(x)$	$t_y(A) = A(y)$
$t_x(\neg C) = \neg C(x)$	$t_y(\neg C) = \neg C(y)$
$t_x(C \sqcap D) = t_x(C) \land t_x(D)$	$t_y(C \sqcap D) = t_y(C) \land t_y(D)$
$t_x(C \sqcup D) = t_x(C) \lor t_x(D)$	$t_y(C \sqcup D) = t_y(C) \lor t_y(D)$
$t_x(\exists P.C) = \exists y. P(x, y) \land t_y(C)$	$t_y(\exists P.C) = \exists x. P(y, x) \land t_x(C)$
$t_x(\forall \mathbf{P.C}) = \forall y. P(x, y) \rightarrow t_y(\mathbf{C})$	$t_y(\forall \mathbf{P.C}) = \forall x. P(y, x) \rightarrow t_x(\mathbf{C})$

 $\sim {\cal ALC} \text{ is a fragment of L2, i.e., FOL with 2 variables, known to be decidable} (NExpTime-complete).}$

Note: FOL with 2 variables is more expressive than ALC (tradeoff expressive power vs. complexity of reasoning).

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DLs as fragments of First Order Logic – Exercise

Translate the following ALC concepts and assertions into L2 formulas (i.e., into FOL formulas that use only variables x and y):

- Father \cap \delta child.(Doctor \cap Manager)
- ② \exists manages.(Company ⊓ \exists employs.Doctor)
- Father $\sqcap \forall$ child.(Doctor $\sqcup \exists$ manages.(Company $\sqcap \exists$ employs.Doctor))
- Person $\sqcap \forall$ child. Happy $\sqsubseteq \exists$ child. \forall child. Happy

Solution:

- Father(x) $\land \forall y. (child(x, y) \rightarrow (Doctor(y) \lor Manager(y)))$
- Father(x) $\land \forall y. (child(x, y) \rightarrow (Doctor(y) \lor \exists x. (manages(y, x) \land (Company(x) \land \exists y. (employs(x, y) \land Doctor(y))))))$

 $\begin{array}{l} \bullet \quad \forall x. \left(\textit{Person}(x) \land \forall y. \textit{child}(x, y) \rightarrow \textit{Happy}(y) \right) \rightarrow \\ (\exists y. \textit{child}(x, y) \land \forall x. \textit{child}(y, x) \rightarrow \textit{Happy}(x)) \end{array}$



The previous translations can be extended to other constructs:

• For inverse roles, swap the variables in the role predicate, i.e.,

 $t_x(\exists P^-.C) = \exists y. P(y,x) \land t_y(C)$ $t_x(\forall P^-.C) = \forall y. P(y,x) \to t_y(C)$ with y a new variable with y a new variable

 $\rightsquigarrow \mathcal{ALCI}$ is still a fragment of L2

 For number restrictions, two variables do not suffice; but, ALCQI is a fragment of C2 (i.e, L2+counting quantifiers)
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 \mathcal{ALC} is a syntactic variant of \mathbf{K}_m (i.e., multi-modal \mathbf{K}):

 $\begin{array}{lll} C \sqcap D & \Leftrightarrow & C \land D & & \exists P.C & \Leftrightarrow & \diamond_P C \\ C \sqcup D & \Leftrightarrow & C \lor D & & \forall P.C & \Leftrightarrow & \Box_P C \\ \neg C & \Leftrightarrow & \neg C & & \end{array}$

- no correspondence for inverse roles
- no correspondence for number restrictions

 \rightsquigarrow Concept consistency, subsumption in $\mathcal{ALC}\Leftrightarrow$ Satisfiability, validity in \mathbf{K}_m

To encode inclusion assertions, axioms are used \rightsquigarrow Logical implication in DLs corresponds to "global logical implication" in Modal Logics

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Relationship	between l	DLs and ontolo	gy formalis	ms

- DLs are nowadays advocated to provide the foundations for ontology languages.
- Different versions of the W3C standard Web Ontology Language (OWL) have been defined as syntactic variants of certain DLs.
- DLs are also ideally suited to capture the fundamental features of conceptual modeling formalism used in information systems design:
 - Entity-Relationship diagrams, used in database conceptual modeling
 - UML Class Diagrams, used in the design phase of software applications
- We briefly overview the correspondence with OWL, highlighting essential DL constructs.
- We will come back a bit later to the correspondence between UML Class Diagrams and DLs.

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DLs vs. OWL				

The Web Ontology Language (OWL) comes in different variants:

- **OWL1 Lite** is a variant of the DL SHIF(D), where:
 - $\bullet~\mathcal{S}$ stands for \mathcal{ALC} extended with transitive roles,
 - H stands for role hierarchies (i.e., role inclusion assertions),
 - ${\mathcal I}$ stands for inverse roles,
 - $\mathcal F$ stands for functionality of roles,
 - $\bullet~(D)$ stand for data types, which are necessary in any practical knowledge representation language.
- **OWL1 DL** is a variant of $\mathcal{SHOIN}(D)$, where:
 - O stands for nominals, which means the possibility of using individuals in the TBox (i.e., the intensional part of the ontology),
 - \mathcal{N} stands for (unqualified) number restrictions.

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DLs vs. OWI	L2			

The latest version standardized by the W3C is **OWL2**: W3C Recommendation of 11/12/2012 http://www.w3.org/2007/0WL/wiki/OWL_Working_Group

- **OWL2 DL** is a variant of SROIQ(D), which adds to OWL1 DL several constructs, while still preserving decidability of reasoning.
 - ${\mathcal Q}$ stands for qualified number restrictions.
 - \mathcal{R} stands for regular role hierarchies, where role chaining might be used in the left-hand side of role inclusion assertions, with suitable acyclicity conditions.
- OWL2 defines also three **profiles**: OWL2 QL, OWL2 EL, OWL2 RL.
 - Each profile corresponds to a syntactic fragment (i.e., a sub-language) of OWL2 DL that is targeted towards a specific use.
 - The restrictions in each profile guarantee better computational properties than those of OWL2 DL.
 - The OWL2 QL profile is derived from the DLs of the *DL-Lite* family (see later).

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DLs vs. other formalisms

DL constructs vs. OWL constructs

OWL constructor	DL constructor	Example
ObjectIntersectionOf	$C_1 \sqcap \cdots \sqcap C_n$	Human ⊓ Male
ObjectUnionOf	$C_1 \sqcup \cdots \sqcup C_n$	Doctor ⊔ Lawyer
ObjectComplementOf	$\neg C$	<i>¬Male</i>
ObjectOneOf	$\{a_1\} \sqcup \cdots \sqcup \{a_n\}$	$\{john\} \sqcup \{mary\}$
ObjectAllValuesFrom	$\forall P.C$	∀hasChild.Doctor
ObjectSomeValuesFrom	$\exists P.C$	∃hasChild.Lawyer
ObjectMaxCardinality	$(\leq n P)$	$(\leq 1 hasChild)$
ObjectMinCardinality	$(\geq n P)$	$(\geq 2 hasChild)$

Note: all constructs come also in the Data... instead of Object... variant.

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DL axioms vs. OWL axioms

OWL axiom	DL syntax	Example
SubClassOf	$C_1 \sqsubseteq C_2$	$Human \sqsubseteq Animal \sqcap Biped$
EquivalentClasses	$C_1 \equiv C_2$	$Man \equiv Human \sqcap Male$
DisjointClasses	$C_1 \sqsubseteq \neg C_2$	$Man \sqsubseteq eg Female$
SameIndividual	$\{a_1\} \equiv \{a_2\}$	$\{presBush\} \equiv \{G.W.Bush\}$
DifferentIndividuals	$\{a_1\} \sqsubseteq \neg \{a_2\}$	${john} \sqsubseteq \neg {peter}$
SubObjectPropertyOf	$P_1 \sqsubseteq P_2$	$has Daughter \sqsubseteq has Child$
EquivalentObjectProperties	$P_1 \equiv P_2$	$hasCost \equiv hasPrice$
InverseObjectProperties	$P_1 \equiv P_2^-$	$hasChild \equiv hasParent^-$
TransitiveObjectProperty	$P^+ \sqsubseteq P$	ancestor $^+ \sqsubseteq$ ancestor
FunctionalObjectProperty	$\top \sqsubseteq (\leq 1 P)$	$\top \sqsubseteq (\leq 1 \text{ hasFather})$

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UML Class Diagrams as ontology formalisms

Reasoning on UML Class Diagrams

We have seen that UML class diagrams are in tight correspondence with ontology languages (in fact, they can be viewed as an ontology language). Let's consider again the two questions we asked before:

1. Can we develop sound, complete, and **terminating** procedures for reasoning on UML Class Diagrams?

- We can exploit the formalization of UML Class Diagrams in **Description** Logics.
- We will see that reasoning on UML Class Diagrams can be done in EXPTIME in general (and actually, it can be carried out by current DLs-based systems such as FACT++, PELLET, or RACER-PRO).

2. How hard is it to reason on UML Class Diagrams in general?

- \bullet We will see that it is $\mathrm{ExpTIME}\textsc{-hard}$ in general.
- However, we can single out **interesting fragments** on which to reason efficiently.

DLs vs. UML Class Diagrams

There is a tight correspondence between variants of DLs and UML Class Diagrams [Berardi, Calvanese, and De Giacomo 2005; Artale et al. 2007].

- We can devise two transformations:
 - \bullet one that associates to each UML Class Diagram ${\cal D}$ a DL TBox ${\cal T}_{{\cal D}}.$
 - one that associates to each DL TBox ${\mathcal T}$ a UML Class Diagram ${\mathcal D}_{{\mathcal T}}.$
- The transformations are not model-preserving, but are based on a correspondence between instantiations of the Class Diagram and models of the associated TBox.
- The transformations are satisfiability-preserving, i.e., a class C is consistent in \mathcal{D} iff the corresponding concept is satisfiable in \mathcal{T} .

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Reducing reasoning in UML to reasoning in DLs

Encoding UML Class Diagrams in DLs

The ideas behind the encoding of a UML Class Diagram ${\cal D}$ in terms of a DL TBox ${\cal T}_{\cal D}$ are quite natural:

- Each class and each datatype is represented by an atomic concept.
- Each attribute is represented by a role.
- Each binary association without association class is represented by a role.
- Each other association is reified, i.e., represented as a concept connected to its components by roles.
- Each part of the diagram is encoded by suitable assertions.

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Encoding of classes and attributes

- A UML class C is represented by an atomic concept C.
- A UML datatype T is represented by an atomic concept T.
- Each attribute a of type T for C is represented by an atomic role a_{c} .
 - To encode the **typing** of *a*:

 $\exists a_C \ \sqsubseteq \ C \qquad \qquad \exists a_C^- \ \sqsubseteq \ T$

• To encode the **multiplicity** [m..n] of a:

 $C \ \sqsubseteq \ (\geq m \, a_{\scriptscriptstyle C}) \sqcap (\leq n \, a_{\scriptscriptstyle C})$

- When m is 0, we omit the first conjunct.
- $\bullet~$ When $n~{\rm is}$ *, we omit the second conjunct.
- When the multiplicity is [0..*] we omit the whole assertion.
- When the multiplicity is missing (i.e., [1..1]), the assertion becomes:

 $C \ \sqsubseteq \ \exists a_C \sqcap (\leq 1 \, a_C)$

Note: We include the name C of the class in the name a_c of the role corresponding to attribute a to take into account that different classes may share attributes.

• The encoding can be extended also to operations of classes.

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Encoding of classes and attributes – Example

 Image: Class cla

- To encode the class *Phone*, we introduce a concept *Phone*.
- Encoding of the attributes *number* and *brand*:

• Encoding of the multiplicities of the attributes *number* and *brand*:

 $\begin{array}{l} \textit{Phone} \ \sqsubseteq \ \exists \textit{number}_{\textit{Phone}} \\ \textit{Phone} \ \sqsubseteq \ \exists \textit{brand}_{\textit{Phone}} \sqcap (\leq 1 \textit{ brand}_{\textit{Phone}}) \end{array}$

• We do not consider the encoding of the operations: *lastDialed()* and *callLength(String)*.

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Encoding of	associations				

The encoding of associations depends on:

- the presence/absence of an association class;
- the arity of the association.

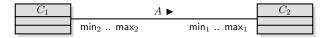
	Without	With
Arity	association class	association class
Binary	via a DL role	via reification
Non-binary	via reification	via reification

Note: an **aggregation** is just a particular kind of binary association without association class and is encoded via a DL role.

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Encoding of binary associations without association class



• An association A between C_1 and C_2 is represented by a DL role A, with:

 $\exists A \sqsubseteq C_1 \qquad \quad \exists A^- \sqsubseteq C_2$

- To encode the multiplicities of A:
 - each instance of class C₁ is connected through association A to at least min₁ and at most max₁ instances of C₂:

 $C_1 \quad \sqsubseteq \quad (\geq \min_1 A) \sqcap (\leq \max_1 A)$

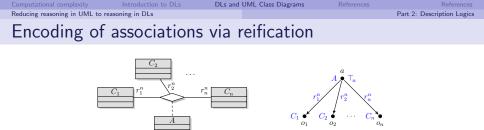
• each instance of class C_2 is connected through association A^- to at least min₂ and at most max₂ instances of C_1 :

 $C_2 \subseteq (\geq \min_2 A^-) \sqcap (\leq \max_2 A^-)$ unibz





Note: an aggregation is just a particular kind of binary association without association class.



- We use a concept T_n that represents all *n*-ary associations.
- Each instance a of T_n represents an instance (o_1, \ldots, o_n) of an association.
- n (binary) roles r_1^n, \ldots, r_n^n are used to connect the object a to the objects o_1, \ldots, o_n representing the components of the tuple.
- To ensure that the instances of T_n correctly represent tuples:

 $\begin{array}{ccc} \exists r_n & \sqsubseteq & \exists r_1^n \sqcap \dots \sqcap \exists r_n^n \sqcap (\leq 1 \, r_1^n) \sqcap \dots \sqcap (\leq 1 \, r_n^n) \\ \exists r_i^n & \sqsubseteq & \exists r_n, & \text{ for } i \in \{1, \dots, n\} \end{array}$

• An *n*-ary association A is then represented by a concept A, with:

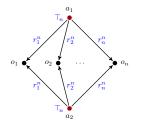
 $A \sqsubseteq \top_n \sqcap \forall r_1^n.C_1 \sqcap \cdots \sqcap \forall r_n^n.C_n$ unibz

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Encoding of associations via reification

We have not ruled out the existence of two instances a_1 , a_2 of concept T_n representing the same instance (o_1, \ldots, o_n) of an *n*-ary association:



To rule out such a situation we could add an identification assertion (see later):

 $(\mathsf{id} \top_n r_1^n, \ldots, r_n^n)$

Note: in a tree-model the above situation cannot occur.

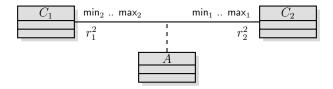
 \rightsquigarrow By the tree-model property of DLs, when reasoning on a KB, we can restrict the attention to tree-models.

Hence we can ignore the identification assertions.

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Multiplicities of binary associations with association class



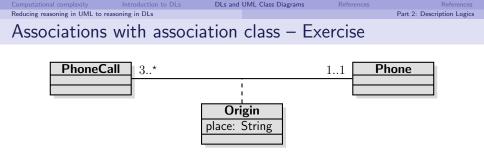
We can encode the multiplicities of association A by means of qualified number restrictions on the inverses of roles r_1^2 and r_2^2 :

• each instance of class C_1 is connected through association A to at least min₁ and at most max₁ instances of C_2 :

$$C_1 \subseteq (\geq \min_1 r_1^2, A) \sqcap (\leq \max_1 r_1^2, A)$$

• each instance of class C_2 is connected through association A^- to at least min₂ and at most max₂ instances of C_1 :

$$C_2 \subseteq (\geq \min_2 r_2^{2^-}, A) \sqcap (\leq \max_2 r_2^{2^-}, A)$$



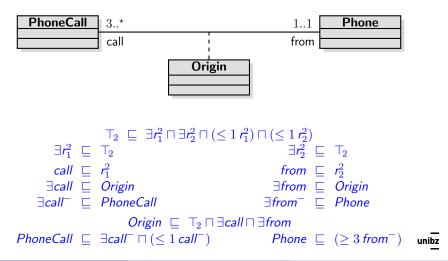
Provide the encoding in DL of the above UML class diagram:

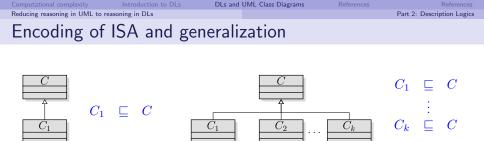
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Associations with association class and named roles

When the roles of the association are explicitly named in the class diagram, we can use such role names, in addition to r_1^n, \ldots, r_n^n .





• When the generalization is **disjoint**:

 $C_i \sqsubseteq \neg C_j$ for $1 \le i < j \le k$

• When the generalization is **complete**:

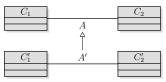
 $C \sqsubseteq C_1 \sqcup \cdots \sqcup C_k$

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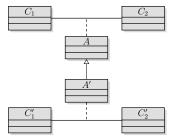
Encoding of ISA between associations

• Without reification:



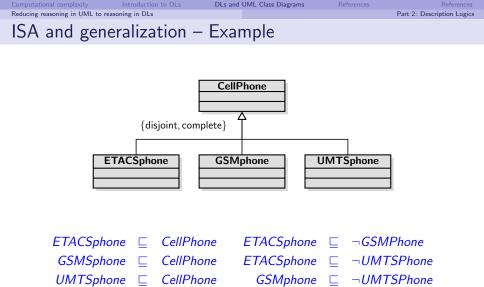
Role inclusion assertion: $A' \sqsubseteq A$

• With reification:

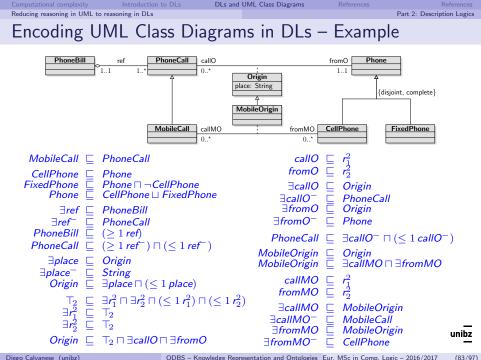


Concept inclusion assertion: $A' \sqsubseteq A$

Remember that we use the same roles r_1^n, \ldots, r_n^n for reification of all *n*-ary associations.



CellPhone \sqsubseteq *ETACSphone* \sqcup *GSMphone* \sqcup *UMTSPhone*



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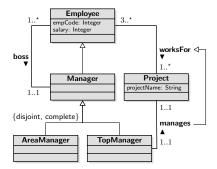
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Encoding UML Class Diagrams in DLs - Exercise





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Reducing reasoning in \mathcal{ALC} to reasoning in UML

We show how to reduce reasoning over \mathcal{ALC} TBoxes to reasoning on UML Class Diagrams:

- We restrict the attention to so-called **primitive** \mathcal{ALC}^- **TBoxes**, where the concept inclusion assertions have a simplified form:
 - there is a single atomic concept on the left-hand side;
 - there is a single concept constructor on the right-hand side.
- Given a primitive ALC^- TBox T, we construct a UML Class Diagram D_T such that:

an atomic concept A in \mathcal{T} is satisfiable iff the corresponding class A in $\mathcal{D}_{\mathcal{T}}$ is satisfiable.

Note: We preserve satisfiability, but do not have a direct correspondence between models of \mathcal{T} and instantiations of $\mathcal{D}_{\mathcal{T}}$.

Encoding DL TBoxes in UML Class Diagrams

Given a primitive \mathcal{ALC}^- TBox \mathcal{T} , we construct $\mathcal{D}_{\mathcal{T}}$ as follows:

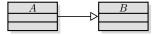
- For each atomic concept A in \mathcal{T} , we introduce in $\mathcal{D}_{\mathcal{T}}$ a class A.
- We introduce in $\mathcal{D}_{\mathcal{T}}$ an additional class O that generalizes all the classes corresponding to atomic concepts.
- For each atomic role P, we introduce in $\mathcal{D}_{\mathcal{T}}$:
 - a class C_P (that reifies P);
 - two functional associations P_1 , P_2 , representing the two components of P.
- For each inclusion assertion in ${\cal T},$ we introduce suitable parts of ${\cal D}_{{\cal T}},$ as shown in the following.

We need to encode the following kinds of inclusion assertions:

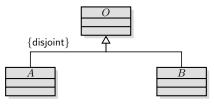
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Encoding of inclusion and of disjointness

For each assertion $A \sqsubseteq B$ of \mathcal{T} , add the following to $\mathcal{D}_{\mathcal{T}}$:

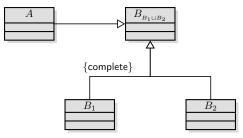


For each assertion $A \sqsubseteq \neg B$ of \mathcal{T} , add the following to $\mathcal{D}_{\mathcal{T}}$:



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Encoding of	union			

For each assertion $A \sqsubseteq B_1 \sqcup B_2$ of \mathcal{T} , introduce an *auxiliary* class $B_{B_1 \sqcup B_2}$, and add the following to $\mathcal{D}_{\mathcal{T}}$:



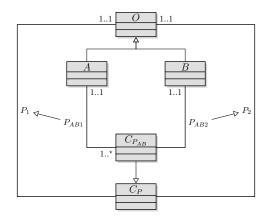
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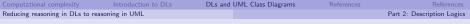
Encoding of existential quantification

For each assertion $A \sqsubseteq \exists P.B$ of \mathcal{T} , introduce

- the auxiliary class $C_{P_{AB}}$, and
- the associations P_{AB1} and P_{AB2} ,

and add the following to $\mathcal{D}_\mathcal{T}$:



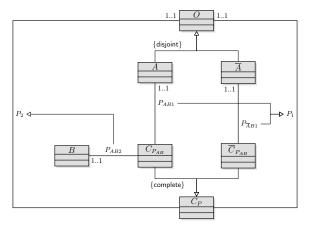


Encoding of universal quantification

For each assertion $A \sqsubseteq \forall P.B$ of \mathcal{T} , introduce (if not already present)

- the auxiliary classes \bar{A} , $C_{P_{AB}}$, and $\overline{C}_{P_{AB}}$, and
- the associations P_{AB1} , $P_{\bar{A}B1}$, and P_{AB2} ,

and add the following to $\mathcal{D}_{\mathcal{T}}$:



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Complexity of reasoning on UML Class Diagrams

Lemma

An atomic concept A in a primitive ALC^- TBox T is satisfiable if and only if the class A is satisfiable in the UML Class Diagram D_T .

Reasoning over primitive ALC^- TBoxes is EXPTIME-hard. From this, we obtain:

Theorem

Reasoning over UML Class Diagrams is EXPTIME-hard.

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Reasoning on UML Class Diagrams using DLs

- The two encodings show that DL TBoxes and UML Class Diagrams essentially have the same computational properties.
- Hence, reasoning over UML Class Diagrams has the same complexity as reasoning over ontologies in expressive DLs, i.e., EXPTIME-complete.
- This is somewhat surprising, since UML Class Diagrams are so widely used and yet reasoning on them (and hence fully understanding the implication they may give rise to), in general is a computationally very hard task.
- The high complexity is caused by:
 - the possibility to use disjunction (covering constraints)
 - the interaction between role inclusions and functionality constraints (maximum 1 cardinality – see encoding of universal and existential quantification)

Note: Without (1) and restricting (2), reasoning becomes simpler [Artale et al. 2007]:

- NLOGSPACE-complete in combined complexity
- in LOGSPACE in data complexity (see later)

Reasoning on UML Class Diagrams

Efficient reasoning on UML Class Diagrams

We are interested in using UML Class Diagrams to specify ontologies in the context of ontology-based data access.

Questions

- Which is the right combination of constructs to allow in UML Class Diagrams to be used for OBDA?
- Are there techniques for query answering in this case that can be derived from Description Logics?
- Can query answering be done efficiently in the size of the data?
- If yes, can we leverage relational database technology for query answering?

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