

Answers to the Sample Exam 20.01.2010

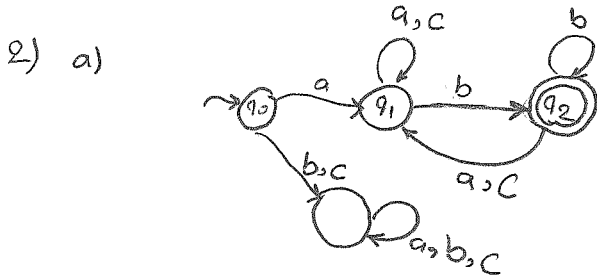
1) a) False, As a counter-example Consider  $L_1 = \Sigma^*$ , and  $L_2$  to be an arbitrary non-regular language. Then  $L_1$  and  $L_2 \cup L_1 = \Sigma^*$  are regular language, and  $L_2$  is not.

b) False, As a counter-example Consider  $L_1 = L_2 = \{\epsilon\}$ , and  $L_3 = \emptyset$ . As a result,  $L_1^* = L_2^* = L_3^* = \{\epsilon\}$ , so  $L_1 \subseteq L_2$  and  $L_2^* \subseteq L_3^*$  but  $L_1 \not\subseteq L_3$

c) True, It is enough to define a finite state automaton, or a regular expression that accepts the language.

Assume that the language  $L$  is  $L_f = \{w_1, w_2, \dots, w_n\}$  where  $n$  is the size of the language. Then the following regular expression accepts  $L_f$ :

$$R_f = w_1 + w_2 + \dots + w_n$$



b) There are a lot of regular expressions that accept the given language some of them are as follows:

$$((x+z)^* (yz)^* (x+z)^*)^*$$

or

$$(x^* z^* (yz)^*)^*$$

or

$$((\epsilon + x + z) (\epsilon + yz) (\epsilon + x + z))^*$$

or

$$(x + z + yz)^*$$

3) a) Having a  $A_\epsilon = (Q, \Sigma, \delta_\epsilon, q_0, F)$  as an  $\epsilon$ -NFA, the NFA which accepts the same language is  $A_N = (Q, \Sigma, \delta_N, q_0, F)$  with  $\delta_N$  defined as follows:

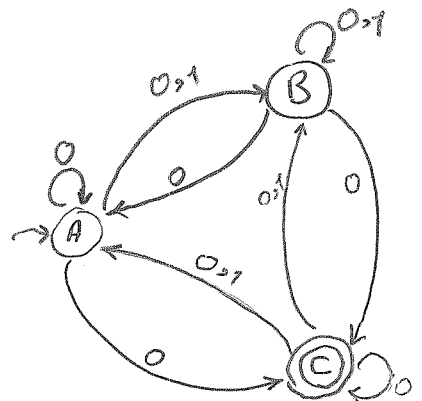
$$\forall q \in Q, \forall a \in \Sigma, \delta_N(q, a) = \bigcap_{P_i \in \epsilon\text{Close}(q)} \delta_\epsilon(P_i, a) = \epsilon\text{Close}\left(\bigcup_{P_i \in \epsilon\text{Close}(q)} \delta_\epsilon(P_i, a)\right)$$

First we compute  $\epsilon\text{Close}(a)$  for all  $a \in \Sigma$

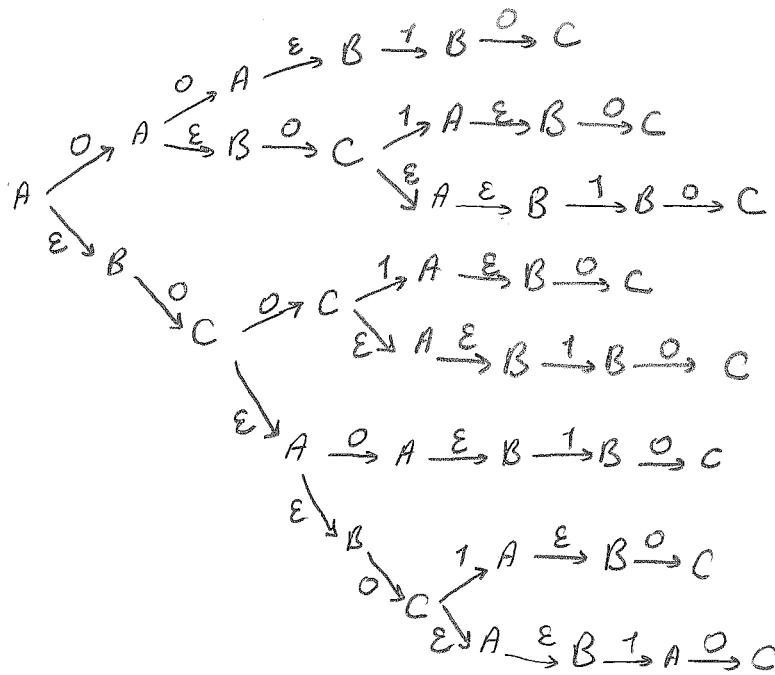
$$\epsilon\text{Close}(A) = \{A, B\} \quad \epsilon\text{Close}(B) = \{B\} \quad \epsilon\text{Close}(C) = \{A, B, C\}$$

Now:

$$\begin{aligned} \delta_N(A, 0) &= \epsilon\text{Close}(\{\delta_\epsilon(A, 0)\}) = \{A, B, C\} \\ \delta_N(A, 1) &= \epsilon\text{Close}(\{\delta_\epsilon(A, 1)\}) = \{B\} \\ \delta_N(B, 0) &= \epsilon\text{Close}(\{\delta_\epsilon(B, 0)\}) = \{A, B, C\} \\ \delta_N(B, 1) &= \epsilon\text{Close}(\{\delta_\epsilon(B, 1)\}) = \{B\} \\ \delta_N(C, 0) &= \epsilon\text{Close}(\{\delta_\epsilon(C, 0)\}) = \{A, B, C\} \\ \delta_N(C, 1) &= \epsilon\text{Close}(\{\delta_\epsilon(C, 1)\}) = \{A, B\} \end{aligned}$$



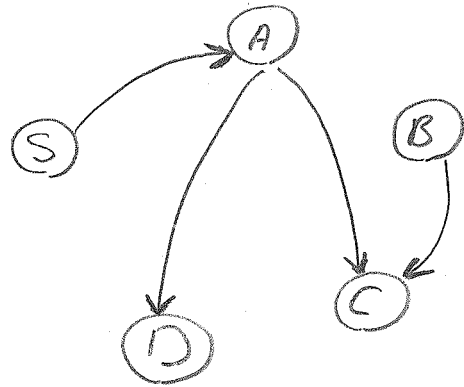
b) Mi:





5) a)

Graph of unit productions:



reachability:  $S \Rightarrow^* A, S \Rightarrow^* C, S \Rightarrow^* D$   
 $A \Rightarrow^* C, A \Rightarrow^* D$   
 $B \Rightarrow^* C$

we get  $G_1 = (V_N, V_T, P_1, S)$  where

$V_N = \{S, A, B, C, D\}, V_T = \{a, b, c, d\}$ ,  $P$  defines as follows:

$S \rightarrow AaBb \mid Da \mid Aa \mid AB \mid aB \mid Ca \mid d \mid dA$

$A \rightarrow Aa \mid AB \mid aB \mid Ca \mid d \mid dA$

$B \rightarrow Bd \mid Cd \mid AB \mid aB \mid Ca$

$C \rightarrow AB \mid aB \mid Ca$

$D \rightarrow d \mid dA$

b)

Generating symbols  $\Sigma_0 = \{a, b, c, d\}$

$\Sigma_1 = \{a, b, c, d, S, A, D\}$

$\Sigma_2 = \{a, b, c, d, S, A, D\}$

So we get  $G_2 = (\{S, D\}, \{a, b, c, d\}, P_2, S)$  where  $P_2$  defines as follows:

$S \rightarrow Da \mid Aa \mid d \mid dA$

$A \rightarrow Aa \mid d \mid dA$

$D \rightarrow d \mid dA$