Data Structures and Algorithms

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Chapter 5

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- Dynamic Data Structures
 - Records, Pointers
 - Lists
- Abstract Data Types
 - Stack, Queue
 - Ordered Lists
 - Priority Queue

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Records

- Records are used to group a number of (different) fields.
- A person record may group name, age, city, nationality, ssn.
- The grouping of fields is a basic and often used technique.
- It is available in all programming languages.

Records in Java

• In java a *class* is used to group fields:

```
class rec { int a; int b; };
public class dummy {
   static rec r;
   public static void main(String args[]) {
     r = new rec();
     r.a = 15; r.b = 8;
     System.out.print("Adding a and b yields ");
     System.out.println(r.a + r.b);
   }
```

Records in C

• In C a *struct* is used to group fields:

```
struct rec {
  int a;
  int b;
};
struct rec r;
int main() {
  r.a = 5; r.b = 8;
  printf("The sum of a and b is %d\n", r.a + r.b);
}
// gcc -o dummy dummy.c ; ./dummy
```

Recursive Data Structures

- The counterpart of recursive functions are recursively defined data structures.
- Example: list of integers

list = { integer integer, list }

• In C:

```
struct list {
   int value;
   Struct list * tail; };
```

Recursive Data Structures/2

- The storage space of recursive data structures is not known in advance.
 - It is determined by the number of elements that will be stored in the list.
 - This is only known during runtime (program execution).
 - The list can **grow** and shrink **during** program execution.

Recursive Data Structures/3

- There must be a mechanism to constrain the initial storage space of recursive data structures (it is potentially infinite).
- There must be a mechanism to grow and shrink the storage space of a recursive data structures during program execution.

Pointers

- A common technique is to allocate the storage space (memory) dynamically.
- That means the storage space is allocated when the program executes.
- The compiler only reserves space for an address to these dynamic parts.
- These addresses are called **pointers**.

Pointers/2

- integer i
- pointer p to an integer (55)
- record r with integer components a (17) and b (24)
- pointer s that points to r

Address	Variable	Memory
1af782	i i	23
1af783	р	1af789
1af784	r	17
1af785		24
1af786	S	1af784
1af787		
1af788		
1af789		55
1af78a		

Pointers in C

- To follow (chase, dereference) a pointer variable we write *p
 - *p = 12
- 2. To get the address of a variable i we write &i
 - p = &i
- 3. To allocate memory we use malloc(sizeof(Type)), which returns an address in the memory heap
 - p = malloc(sizeof(int))
- 4. To free storage space pointed to by a pointer p we use free
 - free(p)

Pointers in C/2

- To declare a pointer to type T we write T*
 int* p
- Note that * is used for two purposes:
 - Declaring a pointer variable
 - Following a pointer *p = 15
- In other languages these are syntactically different.

Pointers in C/3

Address Variable • int i Memory i = 23 23 1af782 1af789 1af783 • int* p p p = malloc(sizeof(int)) 1af784 17 *p = 5524 1af785 • struct rec r 1af786 1af784 S rec.a = 171af787 rec.b = 241af788 • struct rec* s; 55 1af789 s = &r1af78a

Pointers in C/4

Alternative notation:

Variable

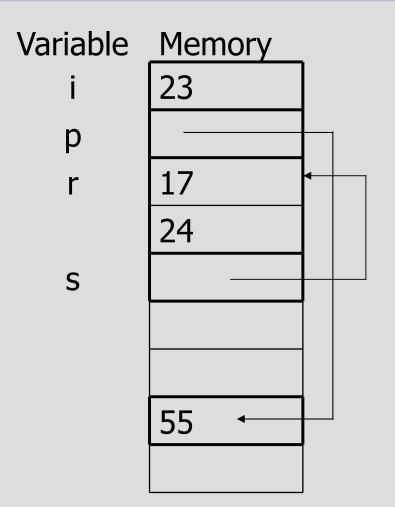
р

r

S

Address	
1af782	
1af783	
1af784	
1af785	
1af786	
1af787	
1af788	
1af789	

Memory
23
1af789
17
24
1af784
55



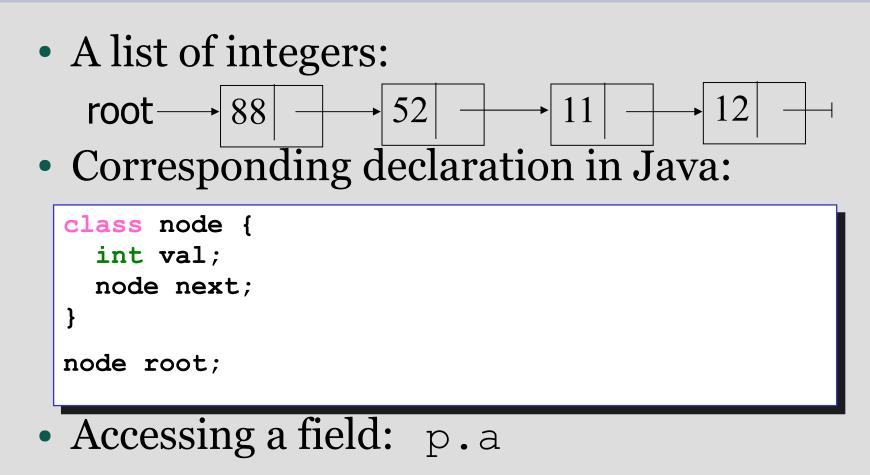
1af78a

Pointers/3

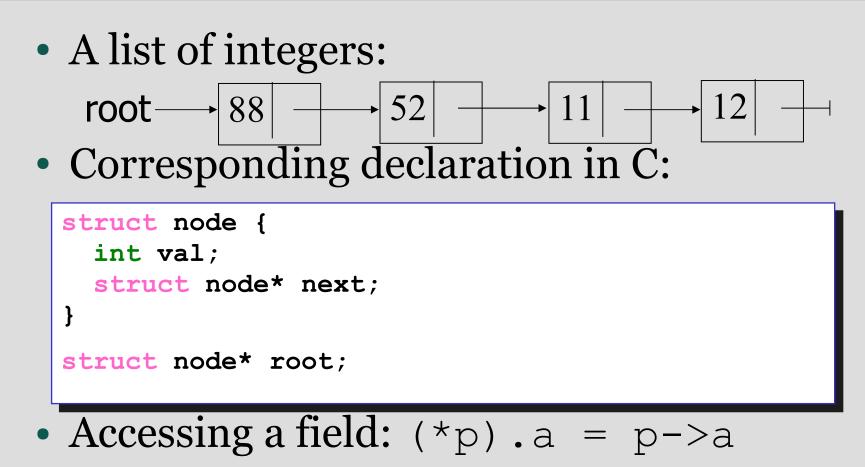
- Pointers are only one mechanism to implement recursive data structures.
- The programmer does not have to be aware of their existence.
 The storage space can be managed automatically.
- In **C** the storage space has to be managed **explicitly**.
- In Java
 - an object is implemented as a pointer.
 - creation of objects (new) automatically allocates storage space.
 - accessing an object will automatically follow the pointer.
 - deallocation is done automatically (garbage collection).

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Lists



Lists/2



Lists/3

• Populating the list with integers (Java): root $\rightarrow 88 \rightarrow 52 \rightarrow 12 \rightarrow 12$

```
root = new node();
root.val = 88;
root.next = new node();
p = root.next;
p.val = 52;
p.next = new node();
p = p.next;
p.val = 12;
p.next = null;
```

Lists/4

- Populating the list with integers (C): root $\rightarrow \boxed{88} \rightarrow \boxed{52} \rightarrow \boxed{12} \rightarrow \boxed{12}$
 - root = malloc(sizeof(struct node));

```
root->val = 88;
root->next = malloc(sizeof(struct node));
```

```
p = root->next;
p.val = 52;
p->next = malloc(sizeof(struct node));
```

```
p = p->next;
p->val = 12;
p->next = NULL;
```

List Traversal

• Print all elements of a list (Java): root \rightarrow 88 \rightarrow 52 \rightarrow 12 \rightarrow

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List Traversal

• Print all elements of a list (C): root \rightarrow 88 \rightarrow 52 \rightarrow 12 \rightarrow

List Insertion

Insert 43 at the beginning (Java):
 root - 88 - 12 -

$$\mathsf{root} \longrightarrow 43 \longrightarrow 88 \longrightarrow 12 \longrightarrow$$

List Insertion

• Insert 43 at the beginning (C): root $\rightarrow 88 \rightarrow 12 \rightarrow 12$

$$\mathsf{root} \longrightarrow 43 \longrightarrow 88 \longrightarrow 12 \longrightarrow$$

List Insertion/2

Insert 43 at end (Java): $root \rightarrow 88$



```
if (root == null) {
  root = new node();
  root.val = 43;
  root.next = null;
} else {
  q = root;
  while (q.next != null) { q = q.next; }
  q.next = new node();
  q.next.val = 43;
  q.next.next = null;
}
```

List Insertion/2

Insert 43 at end (C): root \rightarrow 88 \rightarrow 12 \rightarrow

```
if (root == null) {
  root = malloc(sizeof(struct node));
  root->val = 43;
  root->next = null;
} else {
  q = root;
  while (q->next != null) { q = q->next; }
  q->next = malloc(sizeof(struct node));
  q->next->val = 43;
  q->next->next = null;
}
```

List Deletion

Delete element x from a non-empty list (Java):

```
p = root;
if (p.val == x) {
  root = p.next;
} // no need of freeing in java
else {
  while (p.next != null && p.next.val != x) {
    p = p.next;
  }
  tmp = p.next;
  p.next = tmp.next;
}
```

List Deletion

Delete element x from a non-empty list (C):

```
p = root;
if (p \rightarrow val == x) {
  root = p->next;
  free(p);
} else {
  while (p->next != null && p->next->val != x) {
    p = p - > next;
  tmp = p - > next;
  p->next = tmp->next
  free(tmp);
```

List

- Cost of operations:
 - Insertion at beginning: O(1)
 - Insert at end: O(n)
 - Check isEmpty: O(1)
 - Delete from the beginning: O(1)
 - Search: O(n)
 - Delete: O(n)
 - Print: O(n)

Suggested exercises

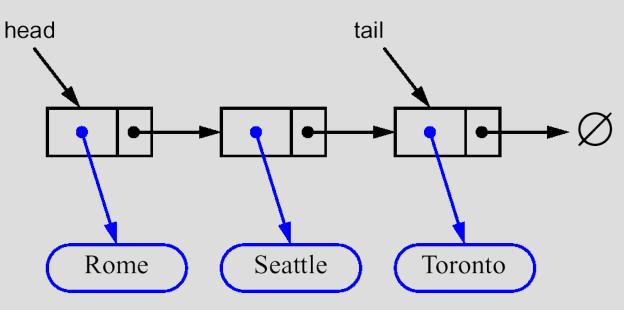
- Implement a linked list with the following functionalities: isEmpty, insertFirst, insertLast, search, deleteFirst, delete, print
- As before, with a recursive version of: insertLast, search, delete, print
 - are recursive versions simpler?
- Implement an efficient version of print which prints the list in reverse order

Variants of linked lists

- Linked lists with explicit head/tail
- Doubly linked lists

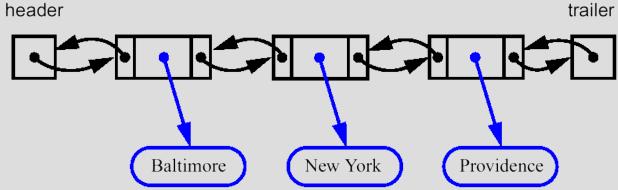
List with Explicit Head/Tail

• Instead of a *root* we can have a *head* and *tail*:

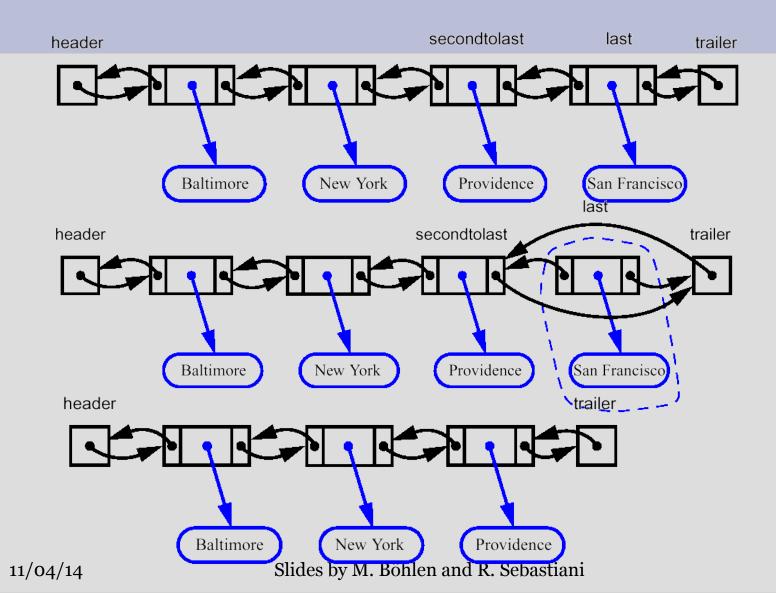


Doubly Linked Lists

• To be able to quickly navigate back and forth in a list we use **doubly linked lists**.



• A node of a doubly linked list has a **next** and a **prev** link.



Data Structures and Algorithms Chapter 5

- Dynamic Data Structures
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Abstract Data Types (ADTs)

- An *ADT* is a mathematically specified entity that defines a set of its *instances*, with:
 - a specific *interface* a collection of signatures of operations that can be invoked on an instance.
 - a set of axioms (preconditions and postconditions) that define the semantics of the operations (i.e., what the operations do to instances of the ADT, but not how).

ADTs/2

• Why ADTs?

- ADTs allows to break work into pieces that can be worked on independently – without compromising correctness.
 - They serve as *specifications* of *requirements* for the building blocks of solutions to algorithmic problems.
- ADTs encapsulate *data structures* and algorithms that *implement* them.

ADTs/3

- Provides a language to talk on a higher level of abstraction.
- Allows to separate the concerns of correctness and the performance analysis
 - Design the algorithm using an ADT
 - 2. Count how often different ADT operations are used
 - 3. Choose implementations of ADT operations
- ADT = Instance variables + procedures
 (Class = Instance variables + methods)

ADTs/4

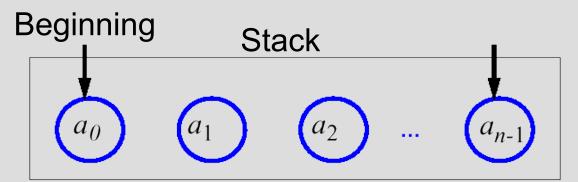
- We discuss a number of popular ADTs:
 - Stacks, Queues
 - Ordered Lists
 - Priority Queues
 - Trees (next chapter)
- They illustrate the use of lists and arrays.

Data Structures and Algorithms Chapter 5

- Dynamic Data Structures
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Stacks

- In a stack, insertions and deletions follow the last-infirst-out (LIFO) principle.
- Thus, the element that has been in the queue for the shortest time are deleted.
 - Example: OS stack, ...
- Solution: Elements are inserted at the **beginning** (push) and removed from the **beginning** (pop).



Slides by M. Böhlen and R. Sebastiani

Stacks/2

• Appropriate data structure:

- Linked list, one root: good
- Array: fastest, limited in size
- Doubly linked list: unnecessary

An Array Implementation

- Create a stack using an array
- A maximum size *N* is specified.
- The stack consists of an N-element array S and one integer variable *count*:
 - *count:* index of the front element (head)
 - *count* represents the position where to insert next element, and the number of elements in the stack

An Array Implementation/2

int size()

return count

```
int isEmpty()
  return (count == 0)
```

```
Element pop()
  if isEmpty() then Error
  x = S[count-1]
  count--;
  return x
```

```
void push(element x)
  if count==N then Error;
  S[count] = x;
  count++;
```

A Linked-List implementation

A list of integers:
root→88→52→11→12→
Insert from the top of the list

```
push(element x):
node p = new node();
p.val = x;
p.next = root;
root = p;
```

Constant-time operation!

A Linked-List implementation

- A list of integers:
 root→88→52→11→12→
 Fytract from the top of the list
- Extract from the top of the list

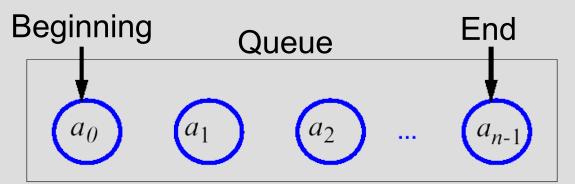
```
Element pop():
```

```
x = root.val;
root = root.next;
Return x;
```

• Constant-time operation!

Queues

- In a queue insertions and deletions follow the **firstin-first-out** (FIFO) principle.
- Thus, the element that has been in the queue for the longest time are deleted.
 - Example: Printer queue, ...
- Solution: Elements are inserted at the **end** (enqueue) and removed from the **beginning** (dequeue).



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Queues/2

• Appropriate data structure:

- Linked list, root: inefficient insertions
- Linked list, head/tail: good
- Array: fastest, limited in size
- Doubly linked list: unnecessary

An Array Implementation

- Create a queue using an array in a circular fashion
- A maximum size *N* is specified.
- The queue consists of an N-element array *Q* and two integer variables:
 - *f*, index of the front element (head, for dequeue)
 - *r*, index of the element after the last one (tail, for enqueue)



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An Array Implementation/2

• "wrapped around" configuration



• what does *f*=*r* mean?

An Array Implementation/3

int size()

```
return (N-f+r) mod N
```

```
int isEmpty()
  return size() == 0
```

```
Element dequeue()
  if isEmpty() then Error
  x = Q[f]
  f = (f+1) mod N
```

return x

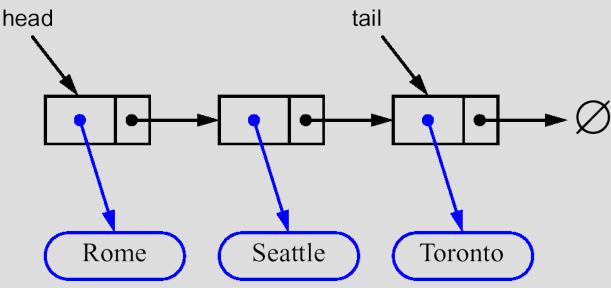
arrays as in Java, with indexes from 0 to n-1

We assume

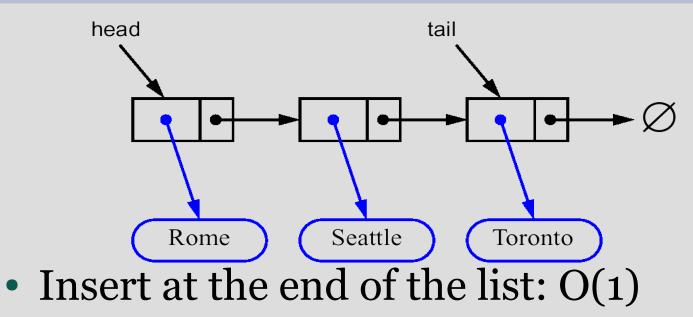
```
void enqueue()
if size()==N-1 then Error
Q[r] = x
r = (r+1) mod N
```

A Linked-List Implementation

- Use linked-list with head and tail
- Insert in tail, extract from head

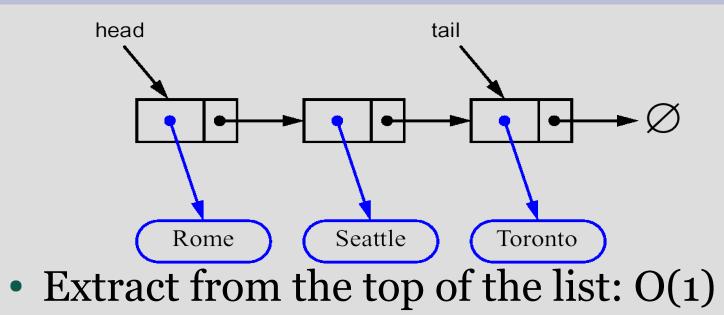


A Linked-List implementation/2



```
enqueue(element x):
node p = new node();
p.info = x; p.next = null;
tail.next=p;
tail=tail.next;
```

A Linked-List implementation/3



```
Element dequeue():
x = root.info;
root = root.next;
Return x;
```

Suggested exercises

- Implement stack and queue as arrays
- Implement stack and queue as linked lists, with the same interface as the array implementation

Suggested exercises/2

- Suppose a queue of integers is implemented with an array of 8 elements: draw the outputs and status of such array after the following operations:
 - enqueue 2,4,3,1,7,6,9
 - dequeue 3 times
 - Enqueue 2,3,4

Can we enqueue any more element?

• Try the same with a stack

• Try similar examples (also with a stack)

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Data Structures and Algorithms Chapter 5

- Dynamic Data Structures
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- Abstract Data Types
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 - Ordered Lists
 - Priority Queue

- In an ordered list elements are ordered according to a key.
- Example functions on ordered list:
 - init()
 - isEmpty()
 - Search (element x)
 - delete (element x)
 - print()
 - insert(element x)

- Declaration of an ordered list identical to unordered list
- Some operations (search, and hence insert and delete) are slightly different

• Insertion into an ordered list (java):

```
void insert(node 1, int x) {
   node p;
   node q;

   if (root == NULL || root.val > x) {
      p = new node();
      p.val = x;
      p.next = root;
      root = p;
   } else {
...
```

• Insertion into an ordered list (java):

```
void insert(node 1, int x) {
  } else {
    p = root;
    while (p.next != NULL && p.next.val < x)</pre>
      p = p.next;
    q = new node();
    q.val = x;
    q.next = p.next;
    p.next = q;
```

• Insertion into an ordered list (C):

```
void insert(struct node* 1, int x) {
  struct node* p;
  struct node* q;

  if (root == NULL || root->val > x) {
    p = malloc(sizeof(struct node));
    p->val = x;
    p->next = root;
    root = p;
  } else {
....
```

• Insertion into an ordered list (C):

```
void insert(struct node* 1, int x) {
  } else {
    p = root;
    while (p->next != NULL && p->next->val < x)</pre>
      p = p - > next;
    q = malloc(sizeof(struct node));
    q->val = x;
    q->next = p->next;
    p->next = q;
```

- Cost of operations:
 - Insertion: O(n)
 - Check is Empty: O(1)
 - Search: O(n)
 - Delete: O(n)
 - Print: O(n)

Suggested exercises

- Implement an ordered list with the following functionalities: isEmpty, insert search, delete, print
- Implement also deleteAllOccurrences()
- As before, with a recursive version of: insert, search, delete, print
 - are recursive versions simpler?
- Implement an efficient version of print which prints the list in reverse order

Data Structures and Algorithms Chapter 5

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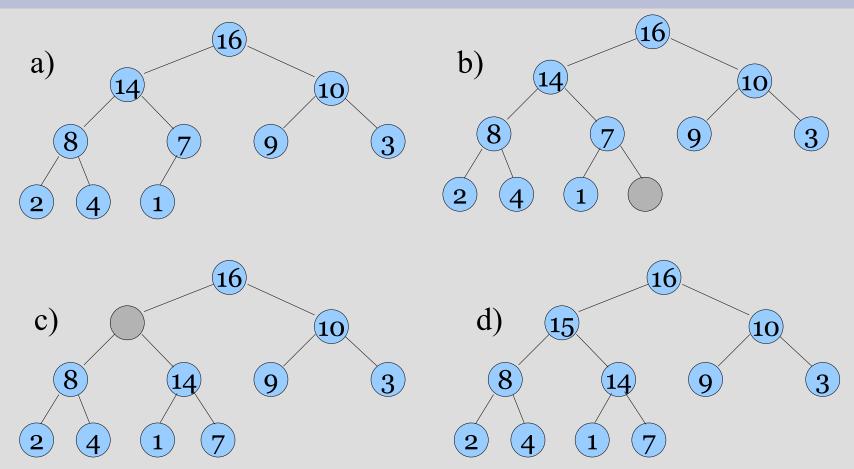
- A priority queue is an *ADT* for maintaining a set S of elements, each with an associated value called key.
- A PQ supports the following operations
 - Insert(S,x) insert element x in set S (S := $S \cup \{x\}$)
 - **ExtractMax**(S) returns and removes the element of S with the largest key
- One way of implementing it: a heap

 Removal of max takes constant time on top of Heapify Θ(log n)

```
ExtractMax(A)
   // removes & returns largest elem of A
   max := A[1]
   A[1] := A[n]
   n := n-1
   Heapify(A, 1, n)
   return max
```

- Insertion of a new element
 - enlarge the PQ and propagate the new element from last place "up" the PQ
 - tree is of height log n, running time: $\Theta(\log n)$

```
Insert(A, key)
n := n+1;
i := n;
while i > 1 and A[parent(i)] < key
    A[i] := A[parent(i)]
    i := parent(i)
    A[i] := key</pre>
```



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- Applications:
 - job scheduling shared computing resources (Unix)
 - Event simulation
 - As a building block for other algorithms
- We used a heap and an array to implement PQ. Other implementations are possible.

Suggested exercises

- Implement a priority queue
- Consider the PQ of previous slides. Draw the status of the PQ after each of the following operations:
 - Insert 17,18,18,19
 - Extract four numbers
 - Insert again 17,18,18,19
- Build a PQ from scratch, adding and inserting elements at will, and draw the status of the PQ after each operation

Summary

- Records, Pointers
- Dynamic Data Structures
 - Lists (root, head/tail, doubly linked)
- Abstract Data Types
 - Type + Functions
 - Stack, Queue
 - Ordered Lists
 - Priority Queues

Next Chapter

- Binary Search Trees
- Red-Black Trees