#### OPTIMAL IMPLEMENTATION OF CONJUNCTIVE QUERIES IN RELATIONAL DATA BASES

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We define the class of conjunctive queries in relational data bases, and the generalized join operator on relations. The generalized join plays an important part in answering conjunctive queries, and it can be implemented using matrix multiplication. It is shown that while answering conjunctive queries is NP complete (general queries are PSPACE complete), one can find an implementation that is within a constant of optimal. The main lemma used to show this is that each conjunctive query has a unique minimal equivalent query (much like minimal finite automata).

1. Example

Given a relation  $R \in D^2$  (as a set of ordered pairs), |D|=n, consider the following question "do there exist elements  $x_1, x_2, x_3, x_4, x_5, x_6$  in D such that

$$\begin{array}{l} R(x_{1}, x_{2}) \land R(x_{3}, x_{2}) \land R(x_{5}, x_{2}) \land R(x_{1}, x_{4}) \\ \land R(x_{3}, x_{4}) \land R(x_{5}, x_{4}) \land R(x_{1}, x_{6}) \land R(x_{3}, x_{6}) \\ \land R(x_{5}, x_{6}) ?" \end{array}$$

This problem may be solved in the obvious way in time  $0(n^6)$ . But it can also be answered in constant time. The answer is "true" iff R is a nonempty relation, for if R(a,b) is true, let  $x_1=x_3=x_5=a$  and  $x_2=x_4=x_6=b$ . This is an (albeit contrived) example of the dramatic improvements in speed possible when answering complex queries in a data base.

### 2. Conjunctive Queries

The relational model of data, introduced by Codd [C70] has gained wide popularity of late [C71a, C71b, C71c, H71, AAFS72, BCKH73, C74, D74, DHP74], and several data base systems have been implemented based on this approach, including PRTV[T76], SEQUEL [CB74], ZETA/TORUS [MST75], INGRES[HSW75], RISS [MM75], RDMS, Tymshare, Query-by-Example [Z75], etc.

Definition. A relational data base

 $B = (D, R_1, R_2, \dots, R_s)$ consists of a nonempty finite set D (the <u>domain</u>) and a finite number of relations  $R_1, \ldots, R_g$  on D. We will sometimes superscript a relation to indicate its rank. Thus  $R_i^p \in D^p$ .

Definition. A first order formula  $\phi$  has the usual quantifiers  $\forall$ ,  $\exists$ , logical connectives  $\lor$ ,  $\land$ ,  $\neg$ , variables  $x_i$  (ranging over the domain D), constants  $a_i$  (taken from a possible infinite set of constants A) and relational operators  $R_i$  (equality is not allowed).

Note: we are using the usual convention of obfuscating names of relations in formulas, with those in a corresponding model (data base). Constants  $a_i$  stand for themselves in the model - this is a slight departure from tradition, and implies that distinct constants stand for distinct elements in the model.

Definition. A first order query is of the form

 $(x_1, x_2, \dots, x_k) \cdot \phi(x_1, \dots, x_k)$ where  $\phi$  is a first-order formula which has no free variables other than those in  $x_1, \dots, x_k$ . The <u>rank</u> of such a query is k. Note: variables cannot be repeated in the vector  $(x_1, \dots, x_k)$  of the query  $(x_1, \dots, x_k) \cdot \phi$ .

<u>Definition</u>. A first order query Q and a data base B are said to be <u>compatible</u> if (i) each relation  $R_i$  in Q is also in the data base B, and (ii) each constant  $a_i$  in Q is an element of the domain D of B.

<u>Definition</u>. Given a query  $Q = (x_1, \dots, x_k) \cdot \phi (x_1, \dots, x_k)$  compatible with a data base B with domain D, the  $\frac{\text{result } \text{Res}(Q,B)}{\{(y_1,\ldots,y_k) \in D^k | \phi(y_1,\ldots,y_k) \text{ is true in } B\}}.$ 

<u>Definition</u>. Two queries  $Q_1, Q_2$  are said to be <u>equivalent</u>  $Q_1 \equiv Q_2$  if for every data base B compatible with both  $Q_1, Q_2$ , Res $(Q_1, B) = \text{Res}(Q_2, B)$ .

Lemma 1. The relation  $\equiv$  above is indeed an equivalence relation.

Reflexivity and symmetry are immediate. For the proof of transitivity see the appendix.

Definition. A boolean query is of the form

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having no free variables. Its result is either "true" (the set containing the empty vector) or "false" (the empty set).

<u>Definition</u>. We define a <u>conjunctive</u> <u>query</u> to be a first order query of the form

 $(x_1, x_2, \dots, x_k)$ .  $\exists x_{k+1} x_{k+2} \dots x_m \cdot A_1 \wedge A_2 \wedge \dots \wedge A_r$ where each  $A_i$  is an atomic formula, i.e. it has the form

 $R_{i}^{p}(y_{1}, \ldots, y_{p})$ 

where each y is either a variable  $x_q, q \le m$ , or a constant  $a_q$ .

The following are examples of conjunctive queries:

(ii) "Give me all second level and higher managers in department K10. Given the following relation for employees: Emp (Name, Salary, Manager, Dept.)

the query is

$$(x_1) \cdot = x_2 x_3 x_4 x_5 x_6 x_7 x_8 \cdot \text{Emp}(x_2, x_3, x_4, x_5)$$
  
  $\wedge \text{Emp}(x_4, x_6, x_1, x_7)$   
  $\wedge \text{Emp}(x_1, x_8, x_9, K10)$ 

(iii) "Are there machine shops x,y such that x supplies some part to y and con- versely". Given relations Output (Shop name, item) and Input (Shop name, item) the query is (). \(\frac{2}{x}, y, z, w.\) Input(x, z) \(\lambda) Input(y, w)\)

Conjunctive queries include a large number of queries actually asked in practice, and even when a more general first order query is needed, parts of it are usually conjunctive. For example, if v's are allowed as well as ^'s in the formula, the query can be expressed as a union of conjunctive queries (after converting the formula into disjunctive normal form) which can then be answered separately. In fact, the language Query-by-Example [Z75] is based on a core of conjunctive queries, and it is this subpart that is learnt and used most readily by the so-called naive user [TG75].

3. <u>Generalized join</u>
<u>Definition</u>. Z<sub>n</sub> = {1,2,...,n}.

Codd [C71G] defined a relational algebra including among others, the following operations on relations which are redefined below with some modifications.

(i) <u>Cartesian product</u>. Given vectors  $v=(x_1,x_2,...,x_p)$  and  $w=(y_1,y_2,...,y_q)$ , v.w denotes the concatenation of v.w

> $v.w = (x_1, \dots, x_p, y_1, \dots, y_q).$ The Cartesian product of relations P,Q is  $P \times Q = \{v.w | v \in P \land w \in Q\}.$

(ii) <u>Intersection</u>, Given relations P,Q of the same rank, their intersection is  $PnQ = \{v | v \in P \land v \in Q\}.$ 

(iii) Permutation. Given a permutation

f on  $Z_p$ , the permutation of a p-ary relation P with respect to f is

$$Perm_{f}(P) = \{(x_{1}, \dots, x_{p}) \mid \\ (x_{f(1)}, \dots, x_{f(p)}) \in P\}$$

(iv) <u>Projection</u>. The projection of a relation P of rank p, p≥1, is

$$Proj(P) = \{ (x_1, \dots, x_{p-1}) \\ \exists x_p, (x_1, \dots, x_p) \in P \}$$

(v) <u>Join</u>. Given relations p<sup>p</sup>,Q<sup>q</sup> and r≤p,q, the join of P,Q is

$$J_{r}(P,Q) = \{(x_{1}, \dots, x_{p-r+q}) | \\ (x_{1}, \dots, x_{p}) \in P \land \\ (x_{p-r+1}, \dots, x_{p-r+q}) \in Q\}$$

In the special case that r=0, join is the same as Cartesian product,

(vi) <u>Restriction</u>. Given r,s, 1≤r<s ≤ p, the restriction of a p-ary relation P is

Restrict<sub>r,s</sub> (P) ={ ( $x_1, ..., x_{s-1}, x_{s+1}, ..., x_p$ ) | ( $x_1, ..., x_{s-1}, x_r, x_s, ..., x_p$ )  $\in$  P}.

- (vii) <u>Selection</u>. Given r≤p, constant a∈A
   (the set of constants) p-ary relation
   P, the selection of P is
   Select<sub>r,a</sub>(P) ={(x<sub>1</sub>,...,x<sub>r-1</sub>,a,x<sub>r+1</sub>,
   ...,x<sub>p</sub>)∈P}.
- (viii) <u>Union</u> Given relations P,Q of the same rank, their union is

 $P \cup Q = \{ v \mid v \in P \lor v \in Q \}$ 

- (ix) <u>Difference</u>. Given the relations P,Q of the same rank, the difference  $P-Q = \{p | p \in P \land p \notin Q\}$
- (x) <u>Division</u>. Given a p-ary relation P,  $p \ge 1$ , and domain D (implicit), the division of P is Div P = { $(x_1, \dots, x_{p-1}) | \forall x_p \in D, (x_1, \dots, x_{p-1}, x_p) \in P$ }

<u>Definition</u>. A <u>relational expression</u> is built up from the domain D, the given relations  $R_i$  and using the relational operators (i) - (x) above. The compatibility of relational expressions and data bases is as for first order queries. The result <u>Res(E,B)</u> of a relational expression E given a compatible data base B is the value of E where  $R_i$ 's and D have the interpretations as assigned by B. Two expressions (or an expression and a query) are <u>equivalent</u> ( $\equiv$ ) if these results are equal for every compatible data base. As before,  $\equiv$  is provably an equivalence relation.

Codd [C71b], using a formalism different from ours (quantifiers in first order queries are over vectors, not elements; there is no domain D; and certain relations such as =, <, < are treated as special) showed that first order queries are essentially the same as relational expressions.

Lemma 2. For each relational expression there is an equivalent first order query, and vice versa.

For the proof see the appendix.

Lemma 3. For each relational expression that uses no operation other than (i)-(vii) above, there is an equivalent conjunctive query, and vice versa.

The proof is similar to that of Lemma 2, and is omitted.

We now define a new operation called generalized join which is a canonical operation for conjunctive queries in the sense that expressions using the generalized join (and selection, restriction) are equivalent to the conjunctive queries.

<u>Definition</u>. Given relations P,Q having ranks p,q respectively, integer r,  $0 \le r \le p+q$ , and injective maps  $f:\mathbb{Z}_p \xrightarrow{Z}_{p+q}$ ,  $g:\mathbb{Z}_q \xrightarrow{Z}_{p+q}$  such that  $\mathbb{Z}_r \xrightarrow{cf(\mathbb{Z}_p) \cup g(\mathbb{Z}_q)}$ , the <u>generalized join</u> of P,Q with respect to r,f,g is defined as

$$J_{r,f,g}^{(P,Q)=\{(x_{1},...,x_{r}) \mid \exists x_{r+1},..., x_{p+q}, \dots, x_{p+q}, \dots, x_{p+q}, \dots, x_{f(p)}, e_{p+q}, \dots, x_{f(p)}, e_{p+q}, \dots, x_{g(q)}, e_{Q}\}}$$

The subscripts r,f,g will be deleted when understood.

The generalized join of two relations corresponds to taking the join of the two relations overlapping on specified columns, followed by the deletion of specified columns. For example, given  $P^4$ ,  $Q^4$ , r=3, f(1)...f(4)=1,2,3,5, and g(1)...g(4)=2,3,4,6, J(P,Q)={(x<sub>1</sub>,x<sub>2</sub>,y<sub>2</sub>)|  $\exists x_3, x_4, y_4$ . P(x<sub>1</sub>,x<sub>2</sub>,x<sub>3</sub>,x<sub>4</sub>)  $\land Q(x_2, y_2, x_3, y_4)$ }

(see Fig. 1). A good way of computing this is by first projecting out the fourth columns of P,Q, and then joining the results:

$$P' = \{ (x_1, x_2, x_3) | \exists x_4 . P(x_1, x_2, x_3, x_4) \} \\ Q' = \{ (y_1, y_2, y_3) | \exists y_4 . Q(y_1, y_2, y_3, y_4) \} \\ J(P,Q) = J(P',Q') = \{ (x_1, x_2, y_2) | \\ \exists x_3 . P'(x_1, x_2, x_3) \land Q'(x_2, y_2, x_3) \}.$$

It may be noted that for each fixed  $x_2$ , J(P,Q) can be obtained as the result of a matrix multiplication:

Let  $J(P,Q)_{x_2} = \{ (x_1, y_2) \mid (x_1, x_2, y_2) \\ \in J(P,Q) \}$   $P'_{x_2} = \{ (x_1, x_3) \mid P'(x_1, x_2, x_3) \}$  $Q'_{x_2} = \{ (x_3, y_2) \mid Q'(x_2, y_2, x_3) \}$ 

and

Then  $J(P,Q)_{x_2} = P'_{x_2} \times Q'_{x_2}$ 

where × is boolean matrix multiplication (treating  $P'_{x_2}$ ,  $Q'_{x_2}$  as boolean matrices). Techniques as those in [S69, ADKF70, FM71] may be used for this purpose.

Several authors [T74, R75, G75, NS76] have considered the problem of efficiently computing joins. What has perhaps not been explicitly stated is that techniques for boolean matrix multiplication can be used to advantage for computing joins (and generalized joins). Most of the published algorithms of which we are aware are similar to sparse matrix multiplication schemes.

Let M(a,b,c) be the time required for computing the product of boolean matrices of size a×b and b×c.

Lemma 4. Given relations  $P \in D^{p}$ ,  $Q \in D^{q}$ , r, f, g as in the definition of generalized joins, let n=|D|,

s=|{i| ∀j.g(j)≠f(i)≤r}|
t=|{i| ∃j.f(i)=g(j)>r}|
u=|{j| ∀i.f(i)≠g(j)≤r}|
v=|{i| ∃j.f(i)=g(j)≤r}|

then  $J_{r,f,g}^{(P,Q)}$  can be computed on a random access machine in time

$$0(n^{p}+n^{q}+n^{r}) + n^{v}.M(n^{s},n^{t},n^{u})$$

This lemma provides, in fact, an application for the multiplication of even highly nonsquare matrices. It may be noted that in the special case when s=t=u=v=0above, the running time can be reduced to 0(1) provided our data structure for relations is either a set of vectors, or a boolean array along with a bit to indicate whether or not it is nonempty.

It is easy to see that relational operations (i)-(v) above are special cases of the generalized join. In fact, even selection would be a special case if we had allowed the construct  $\{a\}$  (where  $a \in A$ is a constant) as an argument to the generalized join; and restriction would be a special case if we relaxed the condition that functions f,g in the definition be injective.

We extend the definition of a relational expression to allow generalized joins as well as operations (i)-(x).

Lemma 5. Every relational expression containing only generalized joins, restriction and selection is equivalent to some conjunctive query; and every conjunctive query is equivalent to some relational expression containing only generalized joins, restriction and selection, and in which selection, restriction are never applied to a subexpression containing a generalized join.

The proof is omitted. The second part of the lemma asserts that restriction, selection operations can be propagated to the bottom of the "expression-tree".

#### Complexity Issues

A query may require exponential time to answer if the desired output is large. However, even boolean queries are complex.

Theorem 6. For data bases B and compatible boolean queries Q, {(Q,B) | Result of Q in B is true} is logspace complete in polynomial space.

In fact, consider the simple data base  $B_0 = (D,R)$  where  $D = \{0,1\}, R = \{0\}$ . Then

<u>Theorem 6'</u>. For the data base  $B_0$  and compatible boolean queries Q, {Q|Result of Q in B is true} is logspace complete, in polynomial space.

Theorems 6,6' follow readily from the completeness of second order propositional calculus.

Theorem 7. For data bases B and compatible conjunctive boolean queries Q, {(B,Q) | Result of Q is true in B}

is logspace complete in NP.

<u>Proof</u>. The set is clearly in NP. Its completeness follows from, say, the completeness of the clique problem for graphs.

Thus boolean first-order queries are PSPACE-complete whereas conjunctive queries are NP-complete. Note that the data base itself is part of the input. Usually, however, queries are substantially shorter than the entire data base. It pays, in such cases, to optimize the query as much as possible, even if such optimization takes a long time with respect to the size of the query (but independent of the data base).

# 5. Query minimization

The main theorem utilized for optimization (Theorem 12) asserts that for every conjunctive query there is a unique (up to renaming of variables) minimal equivalent query, and it is obtained from the original query by "combining variables". This result is similar to the existence of minimal finite automata, which are obtained by "combining states". Unlike the case for deterministic automata, however, minimizing a conjunctive query is NP-hard. In fact, even checking if two given queries are the same except for renaming of variables, turns out to be logspace equivalent to graph isomorphism.

We assume in the sequel, without loss of generality, that in conjunctive queries atomic formulas cannot be repeated.

Definitions. Let  $Q = (x_1, \dots, x_k)$ .  $\exists y_1, \dots, y_p \cdot A_1 \wedge \dots \wedge A_B$  be a conjunctive query. We define  $A_0 = \{a_1, \dots, a_q\}$  to be the set of constants appearing in Q,  $x_{Q} = \{x_{1}, \dots, x_{k}\}, y_{Q} = \{y_{1}, \dots, y_{p}\}.$  We say  $\overline{Q}$  is trivial if  $\overline{A}_Q = X_Q = Y_Q = \{\}$ . The natural <u>model</u>  $M_Q$  of Q is the following algebraic structure: the domain of M<sub>O</sub> is  $D_Q = X_Q \cup Y_Q \cup A_Q$ , and for every relation  $R^r$ in Q,  $r \ge 0$ , the corresponding relation in  $M_{O}$  has value  $\{(z_1, \dots, z_r) \in D_Q^r | R(z_1, \dots, z_r)\}$ is an atomic formula in Q}. In addition,  $M_{O}$  has a finite set of relations taken from the disjoint sets {S1,S2,...},  $\{S_a | a \in A, \text{ the set of constants}\}, which are$ also disjoint from names for relations in data bases. S<sub>i</sub>,S<sub>a</sub> stand for unary relations,  $M_Q$  contains  $S_i$ ,  $1 \le i \le k$ , having value  $\{x_i\}$ , and also  $S_a$  for each  $a \in A_0$ , having value {a}.

<u>Definition</u>. Given a conjunctive query Q as above, a homomorphism  $h: M_Q \rightarrow M_Q$ , and a subset V,  $X_Q \cup A_Q \subset V \subset D_Q$ , such that for all  $z \in V$ , h(z) = z, and for all z,  $h(z) \in V$ , then if Q' is a query such that  $M_Q$ , =  $h(M_Q)$ , we say that Q' is a <u>folding</u> of Q. <u>Definition</u>. If conjunctive queries  $Q_1, Q_2$  are the same except for renaming of variables and reordering of the atomic formulas, and quantified variables, we say that  $Q_1$  and  $Q_2$  are <u>isomorphic</u>.

Note that  $Q_1, Q_2$  are isomorphic iff  $M_{Q_1}$  and  $M_{Q_2}$  are isomorphic.

Theorem 8. Isomorphism of conjunctive queries is logspace equivalent to isomorphism of undirected graphs.

This result, in a slightly different form, has also been shown by Kozen [K76].

Proof. Graph isomorphism is trivially reducible to the isomorphism of boolean conjunctive queries with a single binary relation R such that if R(x,y) is an atomic formula in the query, then so is R(y,x). For the other direction, we first reduce isomorphism of conjunctive queries to that for undirected node-labeled graphs. For query  $Q=(x_1, \ldots, x_k) \cdot \phi$ , the corresponding labeled graph G is constructed as follows. The set of vertices of G includes (i) x<sub>1</sub>,...,x<sub>k</sub>, labeled 1,...,k respectively, (ii) each  $a_i \in A_0$  labeled  $a_i$  itself, (iii) each  $y_i \in Y_0$  labeled by the symbol y, (iv) for each atomic formula  $A_i = R(z_1, \dots, z_r)$  in  $\phi$  there are vertices  $A_{i,j}$ ,  $0 \le j \le r$  of which  $A_{i,0}$  is labeled R, and  $A_{i,j}$  is labeled j' for  $j \ge 1$ , with  $A_{i,0}$ connected to each  $A_{i,j}, j \ge 1$ , and  $A_{i,j}$  connected to the node z. Isomorphism of labeled graphs is easily reduced to isomorphism of unlabeled graphs - the proof is omitted here. П

The next three theorems assert that foldings are Church-Rosser upto isomorphism, that they preserve equivalence of queries, and that they are hard to find in general.

<u>Theorem 9</u>. If queries  $Q_1, Q_2$  are foldings of Q, then there are isomorphic queries  $Q_1', Q_2'$  that are foldings of  $Q_1, Q_2$  respectively.

This follows from Theorems 10, 12 (whose proofs do not use this theorem).

<u>Theorem 10</u>. If  $Q_2$  is a folding of  $Q_1$ , then  $Q_1 \equiv Q_2$ .

<u>Proof.</u> If  $Q_1$  is trivial, so is the theorem. Otherwise let h be the homomorphism folding  $Q_1 = (x_1, \ldots, x_k) \cdot \phi_1(x_1, \ldots, x_k)$ into  $Q_2 = (x_1, \ldots, x_k) \cdot \phi_2(x_1, \ldots, x_k)$ . Since  $\phi_1 \rightarrow \phi_2$  (logical implication) is immediate from the construction, it suffices to show that  $\phi_2 \rightarrow \phi_1$ . Let  $\phi_1 = \exists y_1, \ldots, y_p \cdot A_1 \wedge \ldots \wedge A_r$ ,  $Q_2 = \exists y_1, \ldots, y_i \cdot A_1' \wedge \ldots \wedge A'_s$ . If for any compatible data base, and any  $z_1, \ldots, z_k \in D$ ,  $\phi_2(z_1, \ldots, z_k)$  is true, there exists a mapping f:  $\{y_1, \ldots, y_i\} \rightarrow D$  for which  $A_1' \wedge \ldots \wedge A_s'$  is true. <sup>q</sup> But extending f to g:  $\{y_1, \ldots, y_p\} \rightarrow D$  such that g(y) = f(h(y)), we see, from the definition of folding, that  $\phi_1(z_1, \ldots, z_k)$  is also true.

<u>Theorem 11</u>.  $\{(Q_1,Q_2)|Q_2 \text{ is a folding of } Q_1\}$  is NP complete. This also holds for boolean conjunctive queries.

<u>Proof</u>. It is clearly in NP. To show it is complete, we reduce the graph coloring problem to it. Given a graph G and integer c, we obtain  $Q_1, Q_2$  such that  $Q_2$  is a folding of  $Q_1$  iff G can be c-colored. There is a single binary relation R. Let V be the set of vertices in G, and  $E c V^2$  be the symmetric relation for the set of edges. Let C be a set of c variables disjoint from V. We will also use the elements of V for variables below:

$$Q_{1} = () \cdot \exists v \cdot \exists C \cdot (\bigwedge_{(u,v) \in E} R(u,v)) \land$$
$$(\bigwedge_{\substack{(u,v \in C \\ u \neq v}} R(u,v))$$

$$Q_2 = () \cdot \exists C \cdot \bigwedge_{\substack{u,v \in C}}^{R(u,v)} \cdot \Box$$
$$u \neq v$$

The main theorem of this section asserts that for every conjunctive query there is a minimal equivalent query, unique up to isomorphism, that can be obtained from the original query by folding. It should be noted that folding a query cannot increase the number of variables or atomic formulas in a query, and if the number of variables remains unchanged, the new query is isomorphic to the original.

<u>Theorem 12</u>. For every conjunctive query Q there is a folding  $Q_0$  such that every Q'=Q has a folding Q'<sub>0</sub> isomorphic to  $Q_0$ .

We first prove a lemma.

Lemma 13. For conjunctive queries  $Q_1, Q_2, Q_1 \equiv Q_2$  iff there exist homomorphisms  $R_1: M_{Q_1} \rightarrow M_{Q_2}$ , and  $h_2: M_{Q_2} \rightarrow M_{Q_1}$ .

<u>Proof.</u> If part. Suppose  $h_1, h_2$  exist. Then given a compatible data base B with domain D, let  $(z_1, \ldots, z_k) \in \operatorname{Res}(Q_1, B)$  be any element in the result of  $Q_1$ . Let the matrix of  $Q_1$  (the conjunct of atomic formulas) be satisfied by the mapping  $f:D_Q \rightarrow D$  which is the identity function on  $A_{Q_1}$ , and maps the i-th variable in  $X_Q$  into  $z_1$ . But then, the matrix of  $Q_2$  is also satisfied by the mapping  $g:D_Q \rightarrow D$ ,  $g=f \circ h_2$ , since  $h_2$  is the identity function on  $A_{Q_2}$ , and maps the i-th variable in  $X_Q$  to the I-th variable in  $X_{Q_1}$  (and hence<sup>2</sup>g maps it into  $z_1$ ), and  $|X_{Q_1}| = |X_{Q_2}|$ . Thus  $(z_1, \ldots, z_k) \in \operatorname{Res}(Q_2, B)$ , and it follows that  $\operatorname{Res}(Q_1, B) \subset \operatorname{Res}(Q_2, B)$ . Similarly  $\operatorname{Res}(Q_2, B) \subset \operatorname{Res}(Q_1, B)$ , hence  $Q_1 \equiv Q_2$ .

<u>Only-if part</u>. Suppose Q<sub>1</sub>≡Q<sub>2</sub>. It is trivial that  $|X_{0_1}| = |X_{0_2}|$  (since the matrix of a conjunctive query cannot be equivalent to "false"), and easy to see that  $A_{Q_{4}} = A_{Q_{2}}$ , and for all relations R, if R appears in  $Q_1$ , it also appears in  $Q_2$ . Consider the data base B which is the same as  $M_{O_{4}}$  (without the special relations  $S_{i}$ ,  $S_a$ ).<sup>1</sup> B is compatible with  $Q_1$ ,  $Q_2$ , and  $(x_1, \ldots, x_k) \in \text{Res}(Q_1, B)$ , where  $Q_1$  is of the form  $(x_1, \ldots, x_k) \cdot \phi_1$ . Let  $Q_2$  be of the form  $(x_1', \ldots, x_k) \cdot \phi_2$ . Since  $Q_1 \equiv Q_2$ ,  $(x_1, \ldots, x_k) \in \text{Res}(Q_2, B)$ , i.e. there is a mapping  $h_2: D_Q \rightarrow D_Q$  (D<sub>Q1</sub> is also the domain of B) that is an identity over  $A_{O_{i}}$ , maps x' into x for all i, and such thất if  $R(z_1, \ldots, z_r)$  is an atomic formula in  $Q_2$ ,  $(h_2(z_1)), \ldots, h_2(z_r)) \in \mathbb{R}$  in the model B. But  $h_2$  is a homomorphism from  $M_{Q_1}$  to  $M_{Q_2}$ . Similarly, h<sub>1</sub> exists.

Definition. For any finite model M, if h is a homomorphism  $h: M \rightarrow M$  such that for every homomorpism  $h':h(M) \rightarrow h(M)$ , |h'h(M)| = |h(M)|, we say h(M) is a minimal submodel of M. Clearly, minimal submodels exist for all finite models, any homomorphism  $h':h(M) \rightarrow h(M)$  as above is an automorphism, and h(M) is isomorphic to the submodel induced from M on the domain of h(M). It follows readily that the submodel induced from M on the domain of h(M) is itself a minimal model. We will refer to this as a standard submodel.

Proof of Theorem 12. Given queries Q,Q', let  $Q_0,Q'_0$  be queries such that  $M_{Q_0}, M_{Q'}$  are standard submodels of  $M_Q, M_Q$ , respectively. From the definitions,  $Q_0,Q'_0$ are foldings of Q,Q'. If  $Q \equiv Q'$  then  $Q_0 \equiv Q'_0$  by Theorem 10, and by lemma 13, there exist homomorphisms  $h_1:M_{Q_0} \rightarrow M_{Q'}, h_2:M_{Q'} \rightarrow M_Q$ , but since  $h_1 \circ h_2, h_2 \circ h_1$  must be automorphisms,  $h_1, h_2$  must be isomorphisms. Then by the comment after the definition of isomorphism of queries,  $Q_0, Q'_0$  are isomorphic.

# 6. Model and Optimization

Several optimization concepts have been considered for data bases. "Low-level" concepts such as choosing access paths [eg. CHS76] and deciding when to create a new index [eg. C75] are the most common. Several authors have also considered speeding up the computation of joins [T74, R75, G75]. Considering the statement of Theorem 6, however, it seems that "highlevel" optimizations and heuristics could result in very large speedups for some [SC75] and [NS76] consider queries. changing the order of evaluation of a query represented as an expression using relations and operators (the latter specifically considers conjunctive queries). These optimizations, however, are usually local, and the overall "structure" of the query remains unchanged. In our optimization we first change the query into a minimal

equivalent query, and then choose (globally) an order of computation. The result is an implementation within a constant of optimal in our model, but which we believe would also be good for practical implementations. Computing such an optimal implementation takes time exponential in the size of the query, but is independent of the data base. One also has the option of ameliorating a query (along the suggested lines) for some given period of time rather than optimizing it completely.

# 6.1 The Model

Our model of computation is a straightline program with variables taking relations as values. Statements allowed are (X,Y,Z are variables):

- (a) X+R (R is a given relation)
- (b) X+D (D is the domain)
- (c) X+Perm<sub>f</sub>(Y) (a permutation)
- (d) X+Restrict<sub>r,s</sub>(Y) (a restriction)
- (e) X+Select (Y) ("a" is a constant, r, a  $r \ge 1$ )

(f) X+J<sub>r,f,g</sub>(Y,Z) (a generalized join). The output is the value of a designated variable, say X<sub>0</sub>, at the end of the computation. Further we require that there be no "type-checking" errors in the program thus a variable cannot be used before it is defined, X<sub>0</sub> must be defined in the program, and r,s,f,g, in (c)-(f) above must satisfy the restrictions in the definitions of the corresponding operations. We say a program P is <u>equivalent</u> to a conjunctive query Q (<u>P=Q</u>) if its output (result) equals the result of the query for every data base.

The running time for the program is the sum of the running times for the individual statements. For a data base with domain D, |D|=n, the running times are considered as follows. For statements (a)-(e) the running time is zero. For the generalized join operation (f), let p,q,r,s,t,u,v be as in Lemma 4. Then the running time is  $n^{p} + n^{q} + n^{r} + n^{s+t+u+v}$ . The total running time of a program P on a data base B is denoted <u>Time (P,B)</u>. <u>Definition</u>. Given a conjunctive query Q, a program P is said to be <u>near-optimal</u> for Q if P=Q and there exists a constant c such that for every program P'=Q and every compatible data base B, Time (P,B)  $\leq$ c.Time(P',B).

# Discussion of the Model

Statements (a)-(e) are considered to take zero time. These can, however, be implemented in time independent of n (the size of the domain), by using an array representation for arrays, and changing the access functions when an operator is applied. One could change the model by specifying instead, that these operations take constant time, or time n for (b), and n<sup>p</sup> for (a), (c), (d), (e), where R,Y have rank p. Either way, the results below apply essentially without change. The running time for the generalized join operation is simply the sums of the lengths of the inputs and output, in addition to the time required for the trivial algorithm for boolean matrix multiplication. One could modify the model in the special case when s=t=u=v=0 (see comment following lemma 4), but again the results below apply with little modification.

The model of computation also does not specifically allow the operations of cartesian product, intersection or projection, as these are obtainable from the generalized join operation.

## 6.2 Optimization

The running time of any program is a polynomial in n (the size of the domain) with natural numbers as coefficients. The problem of finding a near optimal program for a given query is of finding one whose polynomial has minimal degree (the degree of the polynomial "zero" is -1 by definition). It suffices, therefore, to consider only expressions using operations (a)-(f) (expressions correspond to programs in which every program variable is used exactly once each on the left and on the right hand side of an assignment, except the output variable  $X_0$  which is used only once on the left hand side). Expressions suffice because for every program there is an equivalent expression whose running time is a polynomial of no higher degree.

<u>Definition</u>. For a program (or expression) P, if T(n) is its running time, then T(n) is a polynomial, and we denote its degree by Deg(P).

<u>Definition</u>. An expression using operators (a)-(f) of Sec. 6.1 is said to have <u>property</u> \* if it is of the form Perm(E×D<sup>k</sup>)

(where we are using × instead of join for clarity) in which E is an expression containing no Perm or D, and in which no subexpression of a selection or restriction contains a join.

Lemma 14. For each program P there is an expression E having property \* such that  $E \equiv P$  and  $Deg(E) \leq Deg(P)$ .

Outline of proof. Represent the program P as a directed acyclic graph, expand it out into an expression (i.e. a tree), delete those occurrences of the domain D which are "joined" with any other "column" of a relation, separate out those occurrences of D that are preserved to the output, and propagate restrictions, selections through joins.

For each expression  $E=Perm(E_1 \times D^K)$  having property \* we associate a conjunctive query Q (we write Q~E) such that Q is equivalent to E, and is constructed from E as in the proof of theorem 2 part 1 (there is a oneone correspondence between the occurrences of atomic formulas in Q and relations in  $E_1$ ). We extend the relation ~ such that if  $Q_1, Q_2$  are isomorphic and  $Q_1$ ~E then also  $Q_2$ ~E.

<u>Lemma 15</u>. Given conjunctive queries  $Q_1, Q_2$ , and expression  $E_1$  such that  $Q_2$  is a folding of  $Q_1$ , and  $Q_1 \sim E_1$ , then there is

an expression  $E_2$  such that  $Q_2 \sim E_2$  and for every compatible data base B, Time  $(Q_2, B) \leq Time (Q_1, B)$ .

Proof is by constructing  $E_2$  from  $E_1$ by deleting those occurrences of relations in  $E_1$  that correspond to atomic formulas in  $Q_1$  which do not occur in  $Q_2$ .

We now outline the algorithm for constructing a near optimal program for a given conjunctive query.

<u>Algorithm</u>. Given a conjunctive query Q, find the minimal query  $Q_1 \equiv Q$ ; then for all expressions E,  $Q_1 \sim E$ , choose the one whose running time is a polynomial of minimal degree. The output is a program that implements this expression.

This algorithm runs in time exponential in the length of the input query (but independent of the data base).

Theorem 16. The above algorithm computes a near-optimal program for the given query.

The proof follows from Theorem 12 and Lemmas 14, 15.

The algorithm can be further speeded up by observing that the expression E can be further restricted such that columns of relations are projected out at the earliest possible moment, i.e. a column is projected out in a join unless it subsequently has to be joined with some other column. This reduces the second part of the algorithm to finding the best order of parenthesizing the matrix of the conjunctive query.

- Example. Given query
  - (x). $\exists$  u,v,w,y,z.  $R(x,v,w) \land R(x,z,w) \land S(u,w) \land S(u,v) \land S(y,w) \land S(y,v) \land S(y,z)$ .

The minimal equivalent query is

(x).∃ u,v,w. R(x,v,w)∧(S(u,w)∧S(u,v))

which can be answered in time  $3n^3+4n^2+n$  by computing

X←{ (v,w) |∃u.S(u,w) ^S(u,v) }

in time  $3n^2+n^3$ , and then the output  $X_0 + \{x | \exists v, w. R(x, v, w) \land T(v, w)\}$ in time  $n+n^2+2n^3$ .

# 7. <u>Conclusions</u>

In this paper we introduce the notion of conjunctive queries and define the operation of "folding" such a query. It is shown that every conjunctive query has a unique (upto isomorphism) minimal equivalent query which can be determined by folding. Since foldings are Church-Rosser, it does not matter in what order one finds foldings. This allows the possibility of finding smaller queries equivalent to a given one without having to obtain the minimal. The minimal query can, however, be used to determine a program whose running time is within a constant of optimal for every data base (in the model of computation which allows algebraic operations on relations).

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# Appendix

<u>Proof of Lemma 1</u>. To show that equivalence of queries is transitive, let  $Q_1 \equiv Q_2$  and  $Q_2 \equiv Q_3$ . Let B be any data base with domain D, compatible with  $Q_1$ ,  $Q_3$ . Let  $\{a_1, \ldots, a_k\}$  and  $\{R_1, \ldots, R_S\}$  be the sets of constants and relations in  $Q_2$ but not in B. Add these to the data base B to obtain data base B' as follows. The domain D' of B' is D  $\cup \{a_1, \ldots, a_k\}$ . Let a be any fixed element of D. Extend the relations in B to B' as follows. If R is an r-ary relation in B, the corresponding relation R' in B' is defined as follows: for any set  $S \in D^S$ , let

$$\begin{split} \mathbf{E(S)} &= \{ (\mathbf{x}_1, \dots, \mathbf{x}_S) \mid \exists (y_1, \dots, y_S) \in S. \\ \forall i \leq s. \text{ if } y_i = a \text{ then } \mathbf{x}_i \in \{a, a_1, \dots, a_k\} \\ \text{else } \mathbf{x}_i = y_i \}. \\ \text{Then } \mathbf{R'} = \mathbf{E(R)}. \quad \text{Also let } \mathbf{R}_1, \dots, \mathbf{R}_S \text{ be empty} \\ \text{in } \mathbf{B'}. \text{ For any first order formula} \end{split}$$

 $\phi(x_1, \dots, x_m)$  with free variables  $(x_1, \dots, x_m)$ , let

 $B(\phi) \stackrel{\text{m}}{=} \{ (y_1, \dots, y_m) \in D^m | B \models \phi (y_1, \dots, y_m) \},$ and B'(\phi) =  $\{ (y_1, \dots, y_m) \in D^{m} | B' \models \phi (y_1, \dots, y_m) \}.$ 

We show by induction on formulas, that  $B'(\phi) = E(B(\phi))$  for formulas compatible with B. It is clearly true for atomic formulas  $R(y_1, \ldots, y_r)$  where each  $y_i$  is a constant or a variable (note: our formulas have no equality or functions). Likewise, it is not difficult to check that if this property holds for  $\phi_1$ ,  $\phi_2$ , it also holds for  $\phi_1^{\wedge \phi_2}$ ,  $\phi_1^{\vee \phi_2}$ ,  $\phi_1^{\vee \phi_1}$ ,  $\forall x \phi_1$ , and for  $\exists x \phi_1$  (note: quantifiers for B range over D, those for B' range over D'). Hence,  $\operatorname{Res}(Q_1,B') = E(\operatorname{Res}(Q_1,B)), \text{ and likewise}$ for  $Q_3$ . But B' is compatible with each of Q1,Q2,Q3, and hence by hypothesis,  $E(Res(Q_1,B)) = Res(Q_1,B') = Res(Q_2,B') =$  $\operatorname{Res}(Q_3,B') = E(\operatorname{Res}(Q_3,B))$ . But the function E is one-one. Hence  $Res(Q_1, B) =$ Res( $Q_3$ , B). This completes the proof.  $\Box$ It may be noted that if equality were allowed in first order formulas, then =

would no longer be transitive in our formalism (where constants in formulas stand for themselves in the interpretation). For consider the boolean queries  $Q_1=(). \forall x.x=a. Q_2=(). \forall x.x=a \land b=b, Q_3=().$ false. Then  $Q_1=Q_2=Q_3$ , but  $Q_1\neq Q_3$  for they differ on the data base with the single element domain D={a}.

This merely points to the pitfalls that may be encountered when formalizing data bases in terms of logic. The alternative would be to allow constants to be mapped into arbitrary elements of the domain by the data base (as in conventional logic). However, as it is usual practice in data base work that constants stand for themselves, one may preface queries by a conjunct asserting that all constants appearing in the query are unequal.

<u>Proof of Lemma 2</u>. <u>Part 1</u>. We show by induction on expressions that for each relational expression there is an equivalent first order query. For expressions D,  $R^r$ , the queries are (x). True,  $(x_1, \ldots, x_r) \cdot R(x_1, \ldots, x_r)$  respectively. For the sequel, let  $(x_1, \ldots, x_p) \cdot \phi_p(x_1, \ldots, x_p)$ and  $(y_1, \ldots, y_q) \cdot \phi_Q(y_1, \ldots, y_q)$  be queries equivalent to expressions P,Q. We will implicitly allow renaming variables where appropriate.

(i) The query equivalent to  $P \times Q$  is  $(x_1, \dots, x_p, y_1, \dots, y_q) \cdot \phi_p \wedge \phi_Q$ 

(ii), (viii), (ix). For  $P \cap Q$ ,  $P \cup Q$ , P - Q, the queries are, respectively

 $\begin{array}{l} (\mathbf{x}_{1},\ldots,\mathbf{x}_{p}) \cdot \phi_{p}(\mathbf{x}_{1},\ldots,\mathbf{x}_{p}) \wedge \phi_{Q}(\mathbf{x}_{1},\ldots,\mathbf{x}_{p}), \\ (\mathbf{x}_{1},\ldots,\mathbf{x}_{p}) \cdot \phi_{p}(\mathbf{x}_{1},\ldots,\mathbf{x}_{p}) \vee \phi_{Q}(\mathbf{x}_{1},\ldots,\mathbf{x}_{p}), \\ \text{and} \\ (\mathbf{x}_{1},\ldots,\mathbf{x}_{p}) \cdot \phi_{p}(\mathbf{x}_{1},\ldots,\mathbf{x}_{p}) \wedge \neg \phi_{Q}(\mathbf{x}_{1},\ldots,\mathbf{x}_{p}). \end{array}$ 

(iii),(iv) For Perm<sub>f</sub>(P), Proj(P), the queries are

$$(x_1, \dots, x_p) \cdot \phi_p(x_{f(1)}, \dots, x_{f(p)}),$$
  
and  
 $(x_1, \dots, x_{p-1}) \cdot \exists x_p \cdot \phi_p(x_1, \dots, x_p)$ 

(v), (vi), (vii), (x). These follow likewise from their definitions. Part 2. We show by induction on formulas that for every first order query, there is an equivalent relational expression. Let the query Q be  $(x_1, \ldots, x_q) \cdot \phi$  and let  $\{x_1, \ldots, x_q, \ldots, x_s\}$  be the set of free and bound variables used in  $\phi$  (after renaming all bound variables such that they are all distinct, and distinct from  $x_1, \ldots, x_q$ ). For a subformula  $\phi'$  of  $\phi$ , we construct an expression equivalent to  $(x_{i,1}, x_{i,2}, \ldots) \cdot \phi'$ , where  $x_{i,1}, x_{i,2}$ . The construction is sketched below.

(i) Let  $R(y_1, \dots, y_r)$  be an atomic formula (where each  $y_i$  is a variable  $x_j$  or a constant) with t (not necessarily distinct) constants and u distinct variables. One can construct an expression by the application of t selections, r-t-u restrictions, and one permutation to  $R \times D^{S-u}$ , that is equivalent to  $(x_1, \dots, x_s) \cdot R(y_1, \dots, y_r)$ .

(ii) Let  $E_1, E_2$  be the expressions for  $\phi_1, \phi_2$ , one can construct the expressions for  $\phi_1 \land \phi_2, \ \phi_1 \lor \phi_2, \ \neg \phi_1$  by permutations and projections on  $E_1, E_2$  followed by intersection, union, and difference (from  $D^k$ ) respectively. Likewise the expressions for  $\exists x \ \phi_1, \ \forall x \phi_1$  are obtained from  $E_1$  by permutation, and projection, division respectively. References

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Fig. 1