

Formal Languages and Compilers

Lecture IV: Regular Languages and Finite Automata

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Formal Languages and Compilers — BSc course

2020/21 – Second Semester

- Regular Expressions (RE).
- Implementing a Recognizer of RE's: Automata.
 - Deterministic Finite Automata (DFA).
 - Nondeterministic Finite Automata (NFA).
 - From Regular Expressions to NFA.
 - ϵ -NFA: NFA with ϵ Transitions.
 - From NFA to DFA.

Regular Grammars, also called **Type 3** Grammars, are formal Grammars, $G = (V_T, V_N, S, P)$, such that all productions in P respect the following condition:

Type 3. $A \rightarrow aB$, or $A \rightarrow a$

with $A, B \in V_N$ and $a \in V_T$.

Furthermore, a rule of the form:

$S \rightarrow \epsilon$

is allowed if S does not appear on the right side of any rule.

- The above define the *Right-Regular Grammars*. The following Productions:
 $A \rightarrow Ba$, or $A \rightarrow a$
define *Left-Regular Grammars*.
- Right-Regular and Left-Regular Grammars define the same set of Languages.
- **Regular Grammars are commonly used to define the lexical structure of programming languages.**

Each **Regular Expression**, say R , denotes a Language, $L(R)$. The following are the rules to build them over an alphabet V :

- 1 If $a \in V \cup \{\epsilon\}$ then a is a Regular Expression denoting the language $\{a\}$;
- 2 If R, S are Regular Expressions denoting the Languages $L(R)$ and $L(S)$ then:
 - 1 $R \mid S$ is a Regular Expression denoting $L(R) \cup L(S)$;
 - 2 $R \cdot S$ is a Regular Expression denoting the concatenation $L(R) \cdot L(S)$, i.e., $L(R) \cdot L(S) = \{r \cdot s \mid r \in L(R) \text{ and } s \in L(S)\}$;
 - 3 R^* (*Kleen closure*) is a Regular Expression denoting $L(R)^*$, zero or more concatenations of $L(R)$, i.e., $L(R)^* = \bigcup_{i=0}^{\infty} L(R)^i$ —where $L(R)^0 = \{\epsilon\}$;
 - 4 (R) is a Regular Expression denoting $L(R)$.

Precedence of Operators: $* > \cdot > \mid$
 $E \mid F \cdot G^* = E \mid (F \cdot (G^*))$

Example. Let $V = \{a, b\}$.

- 1 The Regular Expression $a | b$ denotes the Language $\{a, b\}$.
- 2 The Regular Expression $(a | b)(a | b)$ denotes the Language $\{aa, ab, ba, bb\}$.
- 3 The Regular Expression a^* denotes the Language of all strings of zero or more a 's, $\{\epsilon, a, aa, aaa, \dots\}$.
- 4 The Regular Expression $(a | b)^*$ denotes the Language of all strings of a 's and b 's.

Notational shorthands are introduced for frequently used constructors.

- 1 $+$: *One or more instances*. If R is a Regular Expression then $R^+ \equiv RR^*$.
- 2 $?$: *Zero or one instance*. If R is a Regular Expression then $R? \equiv \epsilon \mid R$.
- 3 *Character Classes*. If $a, b, \dots, z \in V$ then $[a, b, c] \equiv a \mid b \mid c$, and $[a - z] \equiv a \mid b \mid \dots \mid z$.

- **Regular Definitions** are used to give names to regular Expressions and then to re-use these names to build new Regular Expressions.

- A *Regular Definition* is a sequence of definitions of the form:

$\mathbf{D}_1 \rightarrow R_1$

$\mathbf{D}_2 \rightarrow R_2$

...

$\mathbf{D}_n \rightarrow R_n$

Where each \mathbf{D}_i is a distinct name and each R_i is a Regular Expression over the extended alphabet $V \cup \{\mathbf{D}_1, \mathbf{D}_2, \dots, \mathbf{D}_{i-1}\}$.

- **Note:** Such names for Regular Expression will be often the Tokens returned by the Lexical Analyzer. As a convention, names are printed in **boldface**.

Example 1. Identifiers are usually strings of letters and digits beginning with a letter:

letter $\rightarrow A | B | \dots | Z | a | b | \dots | z$

digit $\rightarrow 0 | 1 | \dots | 9$

id $\rightarrow \mathbf{letter(letter | digit)^*}$

Using *Character Classes* we can define identifiers as:

id $\rightarrow [A - Za - z][A - Za - z0 - 9]^*$

Example 2. Numbers are usually strings such as 5230, 3.14, 6.45E4, 1.84E-4.

digit	→	0 1 ... 9
digits	→	digit ⁺
optional-fraction	→	(. digits)?
optional-exponent	→	(E(+ -)? digits)?
num	→	digits optional-fraction optional-exponent

- Languages captured by Regular Expressions could be captured by Regular Grammars (Type 3 Grammars).
- Regular Expressions are a notational variant of Regular Grammars: Usually they give a more compact representation.
- **Example.** The Regular Expression for numbers can be captured by a Regular Grammar with the following Productions (*Num* is the scope and **digit** is a terminal symbol):

Num → **digit** | **digit** *Z*

Z → **digit** | **digit** *Z* | . *Frac-Exp* | **E** *Exp-Num*

Frac-Exp → **digit** | **digit** *Frac-Exp* | **digit** *Exp*

Exp → **E** *Exp-Num*

Exp-Num → +*Digits* | -*Digits* | **digit** | **digit** *Digits*

Digits → **digit** | **digit** *Digits*

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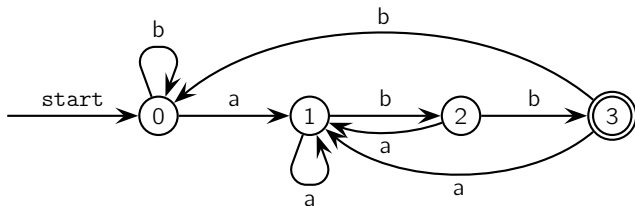
- We need a mechanism to recognize Regular Expressions.
- While Regular Expressions are a *specification language*, **Finite Automata** are their *implementation*.
 - Given an input string, x , and a Regular Language, L , they answer “yes” if $x \in L$ and “no” otherwise.

A **Deterministic Finite Automata**, DFA for short, is a tuple:

$A = (S, V, \delta, s_0, F)$:

- S is a finite non empty set of *states*;
- V is the *input symbol alphabet*;
- $\delta : S \times V \rightarrow S$ is a *total* function called the *Transition Function*;
- $s_0 \in S$ is the *initial state*;
- $F \subseteq S$ is the set of *final states*.

- A DFA can be represented by **Transition Graphs** where the nodes are the states and each labeled edge represents the transition function.
- The **initial state** has an input arch marked **start**.
- **Final states** are indicated by double circles.
- **Example.** DFA that accepts strings in the Language $L((a | b)^* abb)$.



- **Transition Tables** implement transition graphs, and thus Automata.
- A Transition Table has a row for each state and a column for each input symbol.
- The value of the cell (s_i, a_j) is the state that can be reached from state s_i with input a_j .
- **Example.** The table implementing the previous transition graph will have 4 rows and 2 columns, let us call the table δ , then:

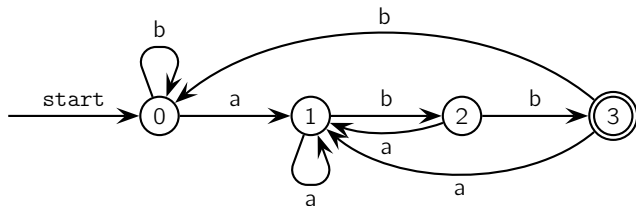
$$\delta(0, a) = 1 \quad \delta(0, b) = 0$$

$$\delta(1, a) = 1 \quad \delta(1, b) = 2$$

$$\delta(2, a) = 1 \quad \delta(2, b) = 3$$

$$\delta(3, a) = 1 \quad \delta(3, b) = 0$$

Example. NFA that accepts strings in the Language $L((a | b)^*abb)$.



	a	b
→ 0	1	0
1	1	2
2	1	3
*3	1	0

To define when an Automaton *accepts* a string we extend the transition function, δ , to a multiple transition function $\hat{\delta} : S \times V^* \rightarrow S$:

$$\hat{\delta}(s, \epsilon) = s$$

$$\hat{\delta}(s, xa) = \delta(\hat{\delta}(s, x), a); \quad \forall x \in V^*, \forall a \in V$$

A DFA accepts an input string, w , if starting from the initial state with w as input the Automaton stops in a final state:

$$\hat{\delta}(s_0, w) = f, \text{ and } f \in F.$$

Language accepted by a DFA, $A = (S, V, \delta, s_0, F)$:

$$L(A) = \{w \in V^* \mid \hat{\delta}(s_0, w) \in F\}$$

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A Finite Automaton is said *Nondeterministic* if we could have more than one transition with a given input symbol.

A *Nondeterministic Finite Automata*, NFA, is a tuple: $A = (S, V, \delta, s_0, F)$:

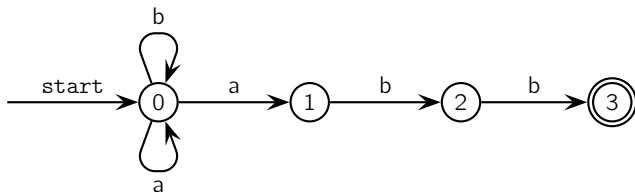
- S is a finite non empty set of *states*;
- V is the *input symbol alphabet*;
- $\delta : S \times V \rightarrow 2^S$ is a *total* function called the *Transition Function*;
- $s_0 \in S$ is the *initial state*;
- $F \subseteq S$ is the set of *final states*.

Note 1. Values in Transition Tables for NFA will be *set of states*.

Note 2. $\delta(s, a)$ may be the *empty set*, i.e., the NFA makes no transition on that input.

Given an input string and an NFA there will be, in general, more than one path that can be followed: **An NFA accepts an input string if there is at least one path ending in a final state.**

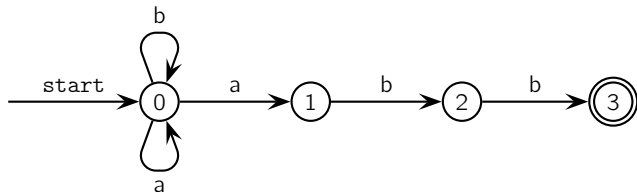
Example. NFA that accepts strings in the Language $L((a | b)^*abb)$.



Exercise. Check that $\delta(0, aaabb)$ is accepted by the above NFA.

Given an input, w , we can represent the computation of a NFA as a **tree of possible execution**, and check for acceptance looking for **at least one path** that ends in a final state.

Example. NFA that accepts strings in the Language $L((a | b)^*abb)$.



	<i>a</i>	<i>b</i>
$\rightarrow 0$	$\{0, 1\}$	$\{0\}$
1	\emptyset	$\{2\}$
2	\emptyset	$\{3\}$
$*3$	\emptyset	\emptyset

To formally define when an NFA *accepts* a string we extend the transition function, δ , to the domain $S \times V^*$:

$$\hat{\delta}(s, \epsilon) = \{s\}$$

$$\hat{\delta}(s, xa) = \bigcup_{s_i \in \hat{\delta}(s, x)} \delta(s_i, a); \quad \forall x \in V^*, \forall a \in V$$

An NFA accepts an input string, w , if starting from the initial state with w as input the Automaton reaches a final state:

$$\exists s. s \in \hat{\delta}(s_0, w), \text{ and } s \in F.$$

Language accepted by a NFA, $A = (S, V, \delta, s_0, F)$:

$$L(A) = \{w \in V^* \mid \hat{\delta}(s_0, w) \cap F \neq \emptyset\}$$

- Both DFA and NFA are capable of recognizing all Regular Languages/Expressions:

$$L(NFA) = L(DFA)$$

- The main difference is a *Space Vs. Time* tradeoff:
 - DFA are faster than NFA;
 - DFA are bigger (exponentially larger) than NFA.

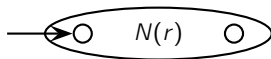
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- The algorithm that generates an NFA for a given Regular Expression (RE) is guided by the syntactic structure of the RE.
- Given a RE, say r , the *Thompson's construction* generates an NFA accepting $L(r)$.
- The Thompson's construction is a **recursive** procedure guided by the structure of the regular expression.

The NFA resulting from the Thompson's construction has important properties:

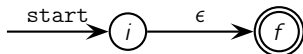
- 1 It is an ϵ -NFA: The automaton can make a transition without consuming an input symbol—the automaton can **non-deterministically** change state;
- 2 It has exactly one final state;
- 3 No edge enters the start state;
- 4 No edge leaves the final state.

Notation: if r is a RE then $N(r)$ is its NFA with transition graph:



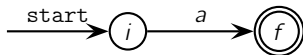
Algorithm RE to NFA: Thompson's Construction

- 1 For ϵ , the NFA is



Where i is the new start state and f the new final state.

- 2 For $a \in V$, the NFA is

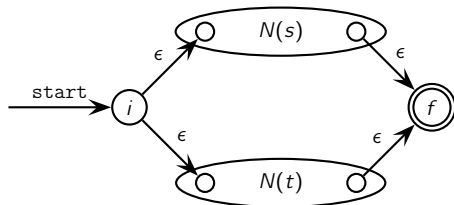


Where i is the new start state and f the new final state.

From Regular Expressions to NFA (4)

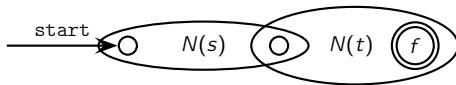
3 Suppose now that $N(s)$ and $N(t)$ are NFA's then

1 For RE $s | t$, the NFA is



Where i and f are the new starting and accepting states, respectively.

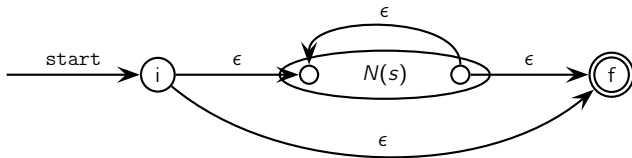
2 For RE st , the NFA is



Where the start state of $N(s)$ is the start state of the new NFA, the final state of $N(t)$ is the final state of the new NFA, the final state of $N(s)$ is merged with the initial state of $N(t)$.

3 (Cont.)

3 For RE s^* , the NFA is



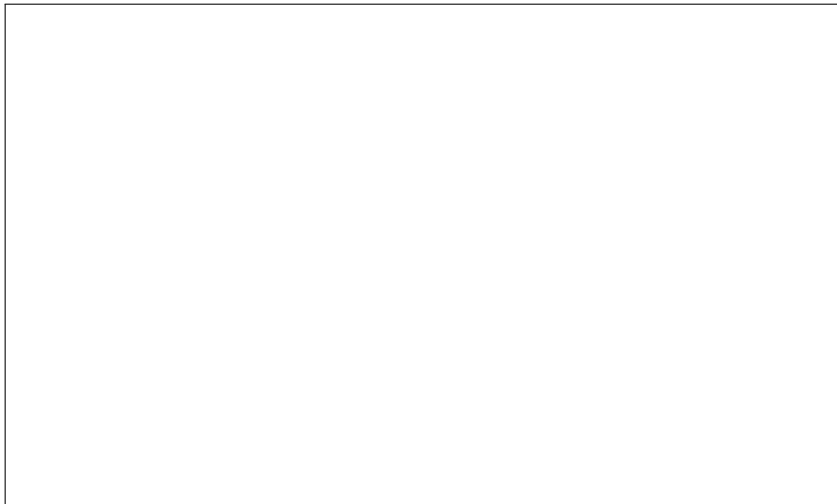
Where i is the new start state and f the new final state.

4 For RE (s) use the same NFA as $N(s)$.

Remarks.

- Every time we insert new states we introduce a new name for them to maintain all the states distinct.
- Even if a symbol appears many times we construct a new NFA for each instance.

Exercise. Build the NFA for the RE $(a \mid b)^*abb$.



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- We can allow state-to-state transitions on ϵ input.
- These transitions are done **spontaneously**, without looking at the input string.
- Useful to compose NFA's (as showed in the Thompson-construction).
- A convenience at times, but still only regular languages are accepted.

Note: See also Prof. J. Ullman slides.

An ϵ -NFA is a tuple: $A_\epsilon = (S, V, \delta, s_0, F)$, where S, V, s_0, F are as for an NFA, and:

$$\delta : S \times (V \cup \{\epsilon\}) \rightarrow 2^S$$

Definition [ϵ -closure]. For $s \in S$, ϵ -closure(s) is the set of all states reachable from s using a sequence of ϵ -moves.

Inductive Definition.

Base. $s \in \epsilon$ -closure(s);

Induction. If $q \in \epsilon$ -closure(s) and $q' \in \delta(q, \epsilon)$, then, $q' \in \epsilon$ -closure(s).

We can extend this notion to **set of states**, $Q \subseteq S$:

$$\epsilon\text{-closure}(Q) = \bigcup_{q_i \in Q} \epsilon\text{-closure}(q_i)$$

We need to define $\hat{\delta}(s, w)$, for $w \in V^*$:

- **Base:** $\hat{\delta}(s, \epsilon) = \epsilon\text{-closure}(s)$.
- **Induction:** $\hat{\delta}(s, x \cdot a) = \bigcup_{s_i \in \hat{\delta}(s, x)} \epsilon\text{-closure}(\delta(s_i, a))$.

Intuition: $\hat{\delta}(s, w)$ is the set of all states reachable from s along paths whose labels on arcs, apart from ϵ -labels, yield w .

Note: The Language recognized by an ϵ -NFA is still defined in the same way as for NFA:

$$L(A_\epsilon) = \{w \in V^* \mid \hat{\delta}(s_0, w) \cap F \neq \emptyset\}$$

- Every NFA is an ϵ -NFA: It just has no transitions on ϵ .
- **Converse:** It requires us to take an ϵ -NFA and construct an NFA that accepts the same language.
- See Lecture Notes by J. Ullman for transforming an ϵ -NFA into an NFA.

Let $A_\epsilon = (S, V, \delta_\epsilon, s_0, F)$, the equivalent NFA, $A_N = (S, V, \delta_N, s_0, F')$, is as follows.

- We compute $\delta_N(s, a)$ as follows:
 - 1 $\delta_N(s, a) = \bigcup_{s_i \in \epsilon\text{-closure}(s)} \delta_\epsilon(s_i, a)$.
- F' is the set of states $s \in S$ such that $\epsilon\text{-closure}(s)$ contains a state of F .

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- NFA are hard to simulate with a computer program.
 - 1 There are many possible paths for a given input string caused by the nondeterminism;
 - 2 The acceptance condition says that there must be *at least one* path ending with a final state;
 - 3 We may need to find all the paths before accepting/excluding a string (BackTracking).
- To map an NFA into an equivalent DFA we use the so called **Subset Construction**.
- *Main Idea*: Each DFA state corresponds to a set of NFA states, thus encoding all the possible states an NFA could reach after reading an input symbol.

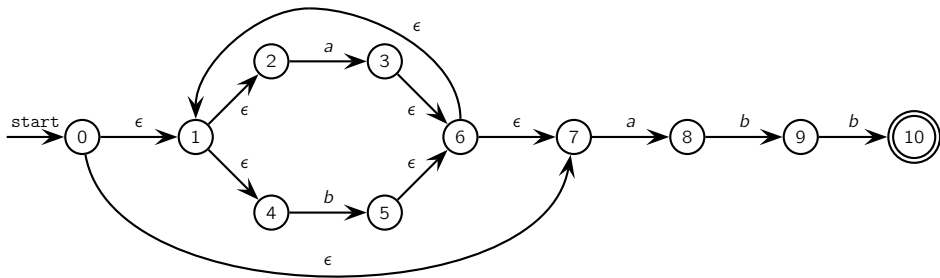
The *Subset Construction* transforms an NFA to an equivalent DFA.

Definition. [NFA to DFA]

Let NFA = $(S_N, V, \delta_N, s_0, F_N)$ then the equivalent DFA = $(S_D, V, \delta_D, s'_0, F_D)$ where:

- $S_D = 2^{S_N}$;
- $s'_0 = \{s_0\}$;
- F_D is the set of states in S_D containing **at least one** element from F_N ;
- $\delta_D(\{s_1, \dots, s_n\}, a) = \{q_1, \dots, q_m\}$
iff $\{q_1, \dots, q_m\} = \bigcup_{s_i \in \{s_1, \dots, s_n\}} \delta_N(s_i, a)$.

ϵ -NFA to NFA to DFA: Exercise



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