

Algorithms for Data Processing

Lecture III: Graph Algorithms – Directed Graphs

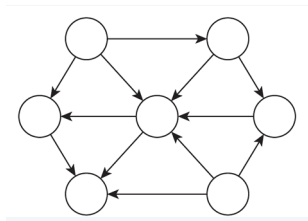
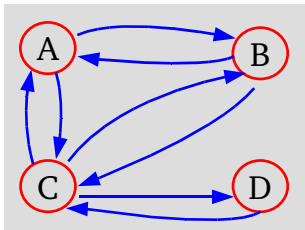
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Directed Graphs

- The general definition of **directed graph** is similar to the definition of graph, except that one associates an **ordered pair** of vertices with each edge.
- Thus each edge of a directed graph can be drawn as an arrow going from the first vertex to the second vertex of the ordered pair.



Representing Directed Graphs: Adjacency List

Each vertex has **two lists** associated with it:

- **Direct List** consists of vertices **to which** it has edges, and
- **Reverse List (G^{rev})** consists of vertices **from which** it has edges.

Search in Directed Graphs

Directed Reachability. Given a node s , find all nodes reachable from s .

Directed s - t shortest path problem. Given two nodes s and t , what is the length of a shortest directed path from s to t ?

Graph search algorithms. BFS/DFS extend naturally to directed graphs to compute **Directed reachability** and **Directed s - t shortest path** using the **Direct List**.

Computing T^{rev} . Given a vertex s , and the Reverse List, G^{rev} , BFS and DFS compute the set of nodes with paths pointing to s .

Strong Connectivity

Def. Vertices u and v are **mutually reachable** if there is both a path from u to v and also a path from v to u .

Def. A graph G is **strongly connected** if every pair of nodes is mutually reachable.



Strong Connectivity/2

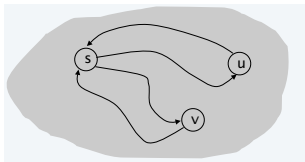
Property. Let s be any vertex. G is strongly connected iff

- every vertex is reachable from s , and
- s is reachable from every vertex.

Proof.

(\Rightarrow) By definition.

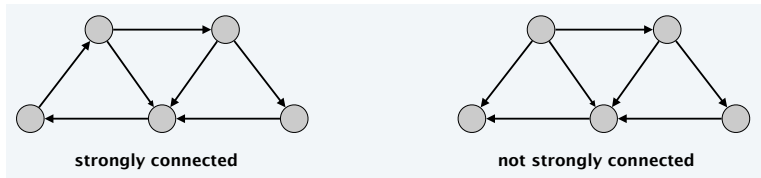
(\Leftarrow) Path from u to v : concatenate $u \rightarrow s$ path with $s \rightarrow v$ path.
Path from v to u : concatenate $v \rightarrow s$ path with $s \rightarrow u$ path.



Strong Connectivity: Algorithm

- Pick any node s .
- Run BFS from s using the Direct List to compute set Discovered.
- Run BFS from s using the Reverse List to compute set Discovered-Rev.
- Return true iff $|\text{Discovered}| = |\text{Discovered-Rev}| = |V|$.

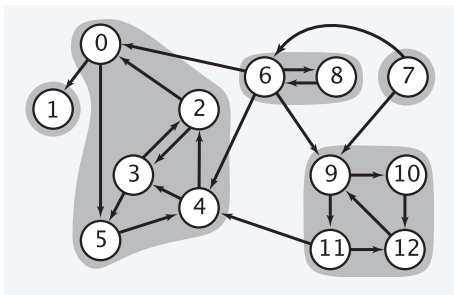
Complexity of Strong Connectivity: $O(m + n)$.



Strong Components

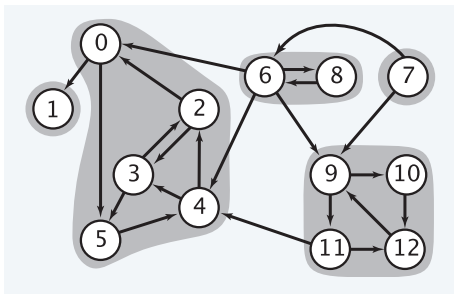
By analogy with connected components in an undirected graph, we can define:

- **Strong component** of a graph as a **maximal subset** of mutually reachable vertices.



Strong Components/2

Property. For any two nodes s and t in a directed graph, their **strong components** are either identical or disjoint.



Strong Components – Tarjan's Algorithm

- Tarjan's algorithm (1972, from the name of it's inventor) is based on depth first search (DFS).
- The vertices are increasingly indexed as they are traversed by the DFS procedure.
- While returning from the recursion of DFS, every vertex v gets assigned a vertex v_R as a representative.
- v_R is a vertex with the least index that can be reached from v .
- Vertices with the same representative are located in the same strongly connected component.

Strong Components – Tarjan's Algorithm/2

Strong-Components(G)

```
index=1; v.index=0, for all  $v \in V$ ;          /* index set to 1 and vertex index set to 0 */
S = [];                                       /* The stack is initialized empty */
for each  $v \in V$                              /* depth-first search for each vertex */ do
  | if  $v.index=0$  then Tarjan(v)              /* that was not already visited */

Tarjan(v);
v.index = index; v.min-index = index;        /* set vertex indices to the current index */
index = index + 1; S.push(v);
for each edge  $(v, v')$  incident to v        /* checks all vertices adjacent to v */ do
  | if  $v'.index=0$  then                       /* vertex not already visited */
    | Tarjan( $v'$ );                             /* DFS Recursion */
    | v.min-index = min(v.min-index,  $v'.min-index$ )
  | else if  $v'$  is inside S then
    | v.min-index = min(v.min-index,  $v'.min-index$ ); /*  $v'$  has a path to v */

if  $v.min-index = v.index$ ; /* v is a representative vertex and an SCC has been found */
then
  | repeat
    |  $v' = S.pop()$ ;
    | output  $v'$ ;                               /* output SCC */
  | until  $(v' \neq v)$ ;
```

Tarjan Complexity

- The For-Loop takes $O(\mathbf{deg}(v))$ time for each vertex v ;
- Thus, in total we need $O(\sum_{v \in V} \mathbf{deg}(v))$;
- From graph properties, $\sum_{v \in V} \mathbf{deg}(v) = 2m$;
- Thus, $O(\sum_{v \in V} \mathbf{deg}(v)) = O(m)$;
- We need $O(n)$ additional time to check whether a vertex has been already visited and to keep the information on whether a vertex is currently inside the stack (e.g., using a boolean array `IsInsideStack[n]`);
- Finally, Tarjan runs in $O(m + n)$.

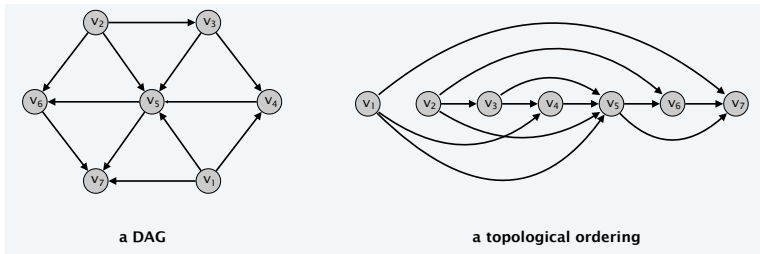
Directed acyclic graphs

A **DAG** is a directed graph that contains no directed cycles

- DAGs can be used to encode *precedence relations* or *dependencies*.
 - ▶ Suppose we have a set of tasks labeled $T_1, T_2 \dots T_n$ that need to be performed, and an edge (i, j) means that T_i must be performed before T_j (*Job Scheduling*).
- Given a set of tasks with dependencies, it would be natural to seek a **valid order** in which the tasks could be performed, so that all dependencies are respected.

Topological Order

A **topological order** of a directed graph $G = (V, E)$ is an ordering of its nodes as v_1, v_2, \dots, v_n so that for every edge (v_i, v_j) we have $i < j$.

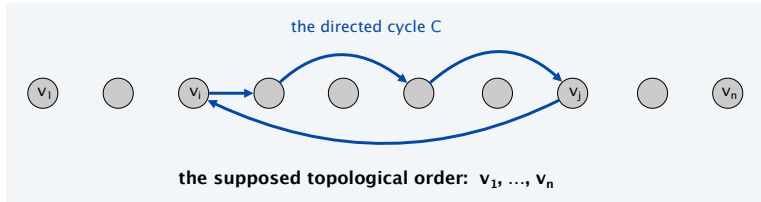


Directed Acyclic Graphs and Topological Order

Property/1. If a directed G has a topological order, then G is a DAG.

Proof by Contradiction.

- Suppose that G has a topological order v_1, v_2, \dots, v_n and that G also has a directed cycle C .
- Let v_i be the lowest-indexed node in C , and let v_j be the node just before v_i ; thus (v_j, v_i) is an edge, and $i < j$.
- On the other hand, since (v_j, v_i) is an edge and v_1, v_2, \dots, v_n is a topological order, we must have $j < i$, a contradiction.



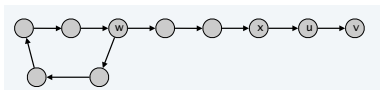
Directed Acyclic Graphs and Topological Order/2

Also the vice-versa holds: If G is a DAG then G has a topological order. We first show the following:

Property/2. If G is a DAG, then G has a node with no entering edges.

Proof by Contradiction.

- Let G be a DAG and every node has at least one entering edge.
- Pick a node v , and follow an edge backward from v . Since v has at least one entering edge (u, v) we can walk backward to u .
- Since u has at least one entering edge (x, u) , we can walk backward to x .
- Repeat until we visit a node, say w , twice.
- Let C denote the sequence of nodes encountered between successive visits to w . C is a cycle.



Directed Acyclic Graphs and Topological Order/3

Property/3. If G is a DAG, then G has a topological ordering.

Proof by Induction on the number of vertices.

- Base case: true if $n = 1$.
- Given DAG with $n > 1$ nodes, find a node v with no entering edges.
- $G \setminus \{v\}$ is a DAG, since deleting v cannot create cycles.
- By inductive hypothesis, $G \setminus \{v\}$ has a topological ordering, say $TO_{G \setminus \{v\}}$.
- Let $TO_G = v, TO_{G \setminus \{v\}}$, this is valid since v has no entering edges.

Topological Order – Algorithm in $O(n^2)$

The following Algorithm applies Property/3 to a DAG to obtain its topological order.

- To find a node with no incoming edges the Reverse List, G^{rev} , is used. This search costs $O(n)$.
- Repeating this step n -times we obtain a final cost of $O(n^2)$.

```
i=1;          /* Initialize i and call Topological-Order(G) */
Topological-Order(G);
Find a node  $v$  in  $G$  with no incoming edges;
if  $v$  does not exist then
  | return
else
  | TO[i] =  $v$ ;
  |  $i=i+1$ ;
  | Topological-Order( $G \setminus \{v\}$ )
```

Topological Order – Algorithm in $O(m + n)$

To achieve a running time of $O(m + n)$ we do the following:

- Maintain the following information with an initialization cost of $O(m + n)$:
 - ▶ $\text{count}[w]$: Array counting the number of incoming edges to each node w ;
 - ▶ S : set of nodes with no incoming edges (can be implemented as a stack or a queue);
- Before each recursive call (the following costs $O(\text{deg}(v))$ time for each vertex v):
 - ▶ remove v from S (e.g., pop v from S);
 - ▶ decrement $\text{count}[w]$ for all edges from v to w , and add w to S if $\text{count}[w] = 0$;

Exercise: Pseudo-code for the Algorithm.

Thank You!