

Programming Paradigms

Unit 2 — Imperative and Object-oriented Paradigm

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Outline

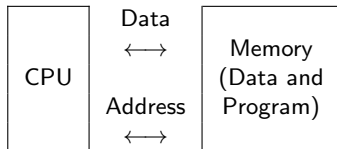
- 1 Imperative Programming Paradigm
- 2 Abstract Data Types
- 3 Object-oriented Approach

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Imperative Paradigm/1

- The **imperative paradigm** is the **oldest** and **most popular** paradigm
- Based on the von Neumann architecture of computers
- Imperative programs define **sequences of commands/statements** for the computer that change a **program state** (i.e., set of variables)
 - Commands are stored in memory and executed in the order found
 - Commands retrieve data, perform a computation, and assign the result to a memory location



- The hardware implementation of almost all computers is imperative
 - Machine code, which is native to the computer, and written in the imperative style

Machine code

```

8B542408 83FA0077 06B80000
C9010000 008D0419 83FA0376
B84AEBF1 5BC3
  
```

Imperative Paradigm/2

- Central elements of imperative paradigm:
 - **Assignment statement**: assigns values to memory locations and changes the current **state** of a program
 - **Variables** refer to memory locations
 - **Step-by-step** execution of commands
 - **Control-flow statements**: Conditional and unconditional (GO TO) branches and loops to change the flow of a program
- Example of computing the factorial of a number:

```
unsigned int n = 5;
unsigned int result = 1;
while(n > 1) {
    result *= n;
    n--;
}
```

Procedural Programming

- **Procedural programming** is a refinement of the imperative paradigm adding subroutines (or procedures)
 - Procedures can be used the same way that built-in commands are used (allows re-usability)
 - Some state changes are localized in this way
- Creating a procedure from the previous example:

```
int factorial(unsigned int n) {
    unsigned int result = 1;
    while(n > 1) {
        result *= n;
        n--;
    }
    return result;
}
```

History of Imperative Paradigm/1

- Earliest imperative languages were the **machine languages** of the computers
 - Very simple instructions
 - Made hardware implementation easier, but difficult to create **complex programs**
- In 1954, **FORTRAN** was developed by John Backus at IBM
 - First major programming language
 - Removed problems of machine code for the creation of complex programs
 - Many features that are common in imperative languages, e.g., named variables, complex expressions, subprograms, etc.
 - FORTRAN was a compiled language
- The next two decades saw the development of a number of other major high-level imperative programming languages
 - In the late 1950s, **ALGOL** (short for **ALGO**rithmic **L**anguage) was developed in order to allow mathematical algorithms to be more easily expressed

History of Imperative Paradigm/2

- **COBOL** (1960) and **BASIC** (1964) were both attempts to make programming **syntax look more like English**
- In the 1970s, Niklaus Wirth at ETH Zurich developed **Pascal** as a small and efficient language intended to **encourage good programming practices** using structured programming and data structuring
- **C** was created by Dennis Ritchie at Bell Laboratories
 - Used to (re-)implement the Unix operating system
 - Has become one of the most widely used programming languages of all time

History of Imperative Paradigm/3

- In the 1980s, there is a rapid growth in interest in **object-oriented programming**
 - **Imperative in style**, but added features to **support objects**
- **Simula** was the first OO-language, and influenced other languages (1960s)
- **Smalltalk-80** was released in 1980 by the Xerox Palo Alto Research Center
- Bjarne Stroustrup designed **C++**, an object-oriented language based on C
- OO languages in the late 1980s and 1990s:
 - Perl (Larry Wall in 1987)
 - Python (Guido van Rossum, 1990)
 - Visual Basic and Visual C++ (Microsoft, 1991 and 1993)
 - PHP (Rasmus Lerdorf, 1994)
 - Java (Sun Microsystems, 1994)
 - Ruby (Yukihiro Matsumoto, 1995)

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Abstract Data Types

- The procedural approach in imperative programming was taken further by introducing **abstract data types (ADT)**
- In ADTs, everything related to a type is **encapsulated** in one bundle, most importantly
 - **data** itself and
 - **operations** on the data
- This **hides** the underlying representation and actual implementation (**information hiding**)

Information Hiding

- What are the advantages of **information hiding**?
 - Allows access to data only via a specified set of operations, thereby **increasing type safety**
 - An implementation of an ADT can be **replaced** by a different (more efficient) one without having to rewrite other parts of the code
 - Code becomes more **portable** and easier to **reuse**

Limits of Data Abstraction

- While ADTs exhibit important features such as encapsulation and information hiding, there are still shortfalls
- We will have a look at these with a concrete (though simplified) example
 - Assume we want to define an ADT implementing a counter

ADT Counter

- This ADT provides a counter of type integer, which can be read, incremented, and reset

```
abstracttype Counter {  
  type  
    Counter = int x;  
  operations  
    int get(Counter x) { return x; };  
    void inc(Counter x) { x++; };  
    void reset(Counter x) { x := 0; };  
}
```

ADT NewCounter/1

- Assume we want to extend this type by adding an operation that tells us how many times we have reset the counter
- We could define a completely new ADT

```
abstracttype NewCounter {  
    type  
        NewCounter = struct {int c;  
                             int noOfResets = 0;}  
    operations  
        int get(NewCounter x) { ...};  
        void inc(NewCounter x) { ...};  
        void reset(NewCounter x) { ...};  
        int howManyResets(NewCounter x) { ...};  
}
```

ADT NewCounter/2

- In terms of encapsulation and information hiding this is fine
- However, we have to **redefine and re-implement** all operations, even though most of them work exactly the same way as in Counter
- Gets worse if we want more extensions to the type Counter or NewCounter
- Adding more types leads to **redundancy**
 - This causes unnecessary work (and increases the size of the code)
 - More difficult to maintain, may result in inconsistencies

ADT NewCounter/3

- Another approach would be to **re-use the ADT Counter** when defining NewCounter

```
abstracttype NewCounter {  
    type  
        NewCounter = struct {Counter c; int noOfResets = 0;}  
    operations  
        int get(NewCounter x) { ... };  
        void inc(NewCounter x) { ... };  
        void reset(NewCounter x) { ... };  
        int howManyResets(NewCounter x) { ... };  
}
```

ADT NewCounter/4

- What would the implementation of the operators look like in this case?
- Re-uses the implementation of Counter:

```
int get(NewCounter x) {  
    return get(x.c);  
}  
...  
void reset(NewCounter x) {  
    reset(x.c);  
    x.noOfResets++;  
}  
...  
}
```

ADT NewCounter/5

- This solution still has drawbacks
 - We have to **map new operators explicitly** to old operators
 - If we extend NewCounter again, an operator is mapped to the NewCounter operator, which is mapped to the Counter operator . . .
 - It would be great if the derived ADT could just **inherit** the operators from the original ADT (→ OO languages)

ADT NewCounter/6

- Further problems with **typing**
- Assume we have a group of counters, some of type Counter and some of type NewCounter
 - If we want to store these in an array, what would the array look like?
 - Counter Z[20] cannot store NewCounter
 - NewCounter Z[20] cannot store Counter

Type Compatibility

- When we introduced type systems, we briefly mentioned compatibility rules, i.e., one type can be substituted for another
- Let us define **type compatibility** between type S and type T in more detail:
 - T is compatible with S when all operations over values of type S are also possible over values of T
 - So `NewCounter` is compatible with `Counter`
- **Substitutability** allows us to use `NewCounter` whenever a `Counter` is expected

ADT NewCounter/7

- Using substitutability we can define an array Counter Z[20] and put counters of type NewCounter into it
- However, what happens if we run the following code?

```
for(int i; i < 20; i++)  
    reset(Z[i]);
```

ADT NewCounter/8

- During compilation a type checker will be satisfied, as `reset()` is a valid operation on `Counter`
- But which version of `reset()` will be executed?
- If this is determined statically (e.g. during compilation), then
 - this will be `reset()` of `Counter`, as `Z` is of type `Counter`
 - As a consequence, `noOfResets` of `NewCounter` will not be updated
- In order to make this work we need to check the “true” type of a counter stored in `Z` and select the correct operator **dynamically**

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Object-oriented Approach

- In the **object-oriented paradigm**, all the previously mentioned issues are resolved
 - There is **encapsulation** and **information hiding**
 - Under certain conditions, **inheritance** of operator implementations is permitted
 - Types can be **substituted** for one another if they are compatible
 - Operators are selected **dynamically** depending on the actual type

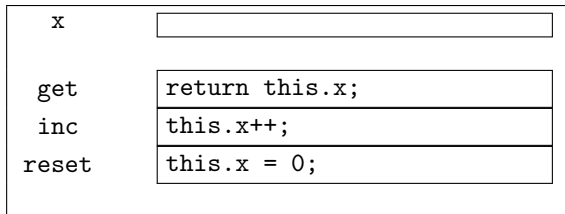
Objects/1

- **Objects** encapsulate both the data and the operations on the data (well, at least conceptually)
- Operations are usually called **methods** and are sent as a message to an object
 - This means, that the object receiving the message is an implicit parameter
 - So for our example, the operations on `Counter` would not need any additional parameters
 - Assuming we have an object `o` implementing a counter, then we would increase it by calling

```
o.inc();
```

Objects/2

- So a **Counter** object would look like this:



- However, when implementing object-oriented languages, the code for operations is not stored explicitly with every object

Classes/1

- A **class** acts as a **blueprint for objects** and basically defines a type

```
class Counter {  
    private:  
        int x;  
    public:  
        int get();  
        void inc();  
        void reset();  
}
```

- Parts declared **private** are not accessible from the outside
- Parts declared **public** are visible to all

Classes/2

- So classes accomplish encapsulation and information hiding
- In addition to this, Counter can be extended in a more elegant way

```
class NewCounter extending Counter {  
    private:  
        int noOfResets = 0;  
    public:  
        void reset() {  
            x := 0;  
            noOfResets++;  
        };  
        int howManyResets() {  
            return noOfResets;  
        };  
}
```

Substitutability

- We also have **substitutability**
 - Every message understood by `Counter` objects is also understood by `NewCounter` objects
- `NewCounter` re-uses the methods `get()` and `inc()`
- it redefines the method `reset()`
 - This is also called **overriding**
- It also defines a new method `howManyResets()`
 - Clearly, additional methods do not pose a problem for substitutability

Inheritance

- We also say that all the methods that are not redefined inherit their implementation from the superclass
- Some languages (such as C++) allow **multiple inheritance**
 - That means a class can have more than one superclass
 - Can be problematic due to name clashes

Substitutability and Inheritance

- Although some languages implement substitutability and inheritance using the same constructs, these are different concepts
 - **Substitutability** allows the **use of an object** in another context
 - Object does not have to be of a subclass to understand same methods
 - **Inheritance** allows the **re-use of code** (for methods)
 - Private inheritance in C++ re-uses code, but does not allow substitutability

Dynamic Method Lookup/1

- A method defined for one object can be **redefined** in objects belonging to other classes
- That means there can be many versions of a method
- In order to figure out which one to use, we have to look at the actual type of the object the message is sent to
- This is also called **dynamic dispatch**

Dynamic Method Lookup/2

- Looking at our Counter example in an object-oriented setting

```
for(int i; i < 20; i++)  
    reset(Z[i]);
```

gives us the correct results using dynamic dispatch

- Not to be confused with **operator overloading**, in which multiple versions of a method with different parameters can exist, e.g.,

```
void reset();  
void reset(int a);  
int reset();
```

- Correct method would be selected by matching its **signature**

Polymorphism

- Nevertheless, dynamic method lookup and operator overloading are different facets of **polymorphism**
- Polymorphism means that an object or method can have more than one form
- Yet another kind of polymorphism is **parametric polymorphism** or **generics**
 - Also called **templates** in C++

Generics

- **Generics** consist of program fragments, where some types are indicated by parameters
- These parameters can then be **instantiated** by “concrete” types
- Depending on the generics, the type used for instantiation has to implement certain methods

Generics Example

- Implement a stack without having to re-implement it for every possible data type of its content

```
class Elem <A> {
    A content;
    Elem <A> next;
}
class Stack <A> {
    private:
        Elem <A> top = null;
    public:
        boolean isEmpty();
        void push(A object);
        A pop();
}
```

Summary

- **Imperative paradigm** is the **oldest** programming paradigm, based on von Neumann architecture
 - Program consists of **sequence of statements** that change the program state
- **Procedural programming** is a refinement that makes it easier to write complex programs
- **Machine languages** were the earliest imperative languages, followed by FORTRAN and ALGOL
- **Abstract Data Types** is a further extension of imperative programming
 - **Data** and **operations** are **encapsulated** into a bundle (**information hiding**)
 - This hides the underlying representation and implementation
- **Object-oriented paradigm** extends ADTs
 - **Classes** are **blueprints** for objects that encapsulate both data and operations
 - Objects exchange **messages**
 - Provides **encapsulation**, **information hiding**, **inheritance**, and **dynamic dispatching**